

12A, 28V_{IN} DC/DC µModule Regulator with PLL, Output Tracking and Margining

Complete Switch Mode Power Supply

- Wide Input Voltage Range: 4.5V to 28V
- 12A DC Typical, 14A Peak Output Current
- 0.6V to 5V Output Voltage

FEATURES

- Output Voltage Tracking and Margining
- Redundant Mounting Pads for Enhanced Solder-Joint Strength
- Parallel Multiple µModule® Regulators for Current Sharing
- Differential Remote Sensing for Precision Regulation
- PLL Frequency Synchronization
- ±1.5% Total DC Error
- Current Foldback Protection (Disabled at Start-Up)
- Pb-Free RoHS Compliant Package Gold Finish LGA (e4) or SAC 305 BGA (e1)
- -55°C to 125°C Operating Temperature Range (LTM4601AHVMPV)
- Ultrafast[™] Transient Response
- Up to 95% Efficiency at 5V_{IN}, 3.3V_{OUT}
- Programmable Soft-Start
- Output Overvoltage Protection
- Enhanced (15mm × 15mm × 2.82mm) Surface Mount LGA and (15mm × 15mm × 3.42mm) BGA Packages

APPLICATIONS

- Telecom, Industrial and Networking Equipment
- Military and Avionics Systems

DESCRIPTION

The LTM $^{\circ}$ 4601AHV is a complete 12A step-down switch mode DC/DC power supply with onboard switching controller, MOSFETs, inductor and all support components. The μ Module regulator is housed in a small surface mount 15mm \times 15mm \times 2.82mm LGA or 15mm \times 15mm \times 3.42mm BGA package. The LTM4601AHV LGA and BGA packages are designed with redundant mounting pads to enhance solder-joint strength for extended temperature cycling endurance. Operating over an input voltage range of 4.5V to 28V, the LTM4601AHV supports an output voltage range of 0.6V to 5V as well as output voltage tracking and margining. The high efficiency design delivers 12A continuous current (14A peak). Only bulk input and output capacitors are needed to complete the design.

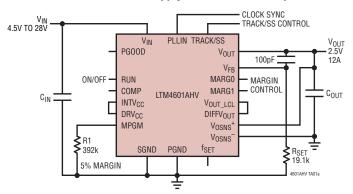
The low profile and light weight package easily mounts in unused space on the back side of PC boards for high density point of load regulation. The µModule regulator can be synchronized with an external clock for reducing undesirable frequency harmonics and allows PolyPhase® operation for high load currents.

An onboard differential remote sense amplifier can be used to accurately regulate an output voltage independent of load current.

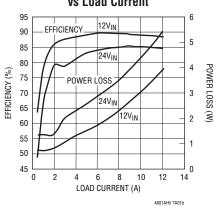
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TYPICAL APPLICATION

2.5V/12A Power Supply with 4.5V to 28V Input



Efficiency and Power Loss vs Load Current





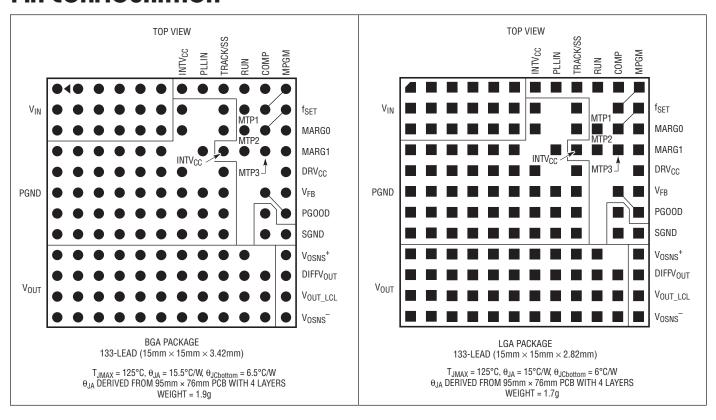
ABSOLUTE MAXIMUM RATINGS

(Note 1)

 $INTV_{CC}$, DRV_{CC} , V_{OUT} LCL, V_{OUT} ($V_{OUT} \le 3.3V$ with Remote Sense Amp)-0.3V to 6V PLLIN, TRACK/SS, MPGM, MARGO, MARG1, RUN -0.3V to 5V V_{FB}, COMP......-0.3V to 2.7V V_{IN} –0.3V to 28V

Operating Temperature Range (Note 2)
E and I Grades40°C to 85°C
MP Grade55°C to 125°C
Junction Temperature 125°C
Storage Temperature Range55°C to 125°C

PIN CONFIGURATION



ORDER INFORMATION

LEAD FREE FINISH	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE (NOTE 2)
LTM4601AHVEV#PBF	LTM4601AHVV	133-Lead (15mm × 15mm × 2.82mm) LGA	-40°C to 85°C
LTM4601AHVIV#PBF	LTM4601AHVV	133-Lead (15mm \times 15mm \times 2.82mm) LGA	-40°C to 85°C
LTM4601AHVMPV#PBF	LTM4601AHVMPV	133-Lead (15mm × 15mm × 2.82mm) LGA	−55°C to 125°C
LTM4601AHVEY#PBF	LTM4601AHVY	133-Lead (15mm \times 15mm \times 3.42mm) BGA	-40°C to 85°C
LTM4601AHVIY#PBF	LTM4601AHVY	133-Lead (15mm × 15mm × 3.42mm) BGA	-40°C to 85°C
LTM4601AHVMPY#PBF	LTM4601AHVMPY	133-Lead (15mm × 15mm × 3.42mm) BGA	−55°C to 125°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. *The temperature grade is identified by a label on the shipping container. For more information on lead free part marking, go to: http://www.linear.com/leadfree/ This product is only offered in trays. For more information go to: http://www.linear.com/packaging/



ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the specified operating temperature range (Note 2). Otherwise specifications are at $T_A = 25^{\circ}C$, $V_{IN} = 12V$, per typical application (front page) configuration, $R_{SET} = 40.2k$.

SYMBOL	PARAMETER	CONDITIONS	CONDITIONS				UNITS
V _{IN(DC)}	Input DC Voltage		•	4.5		28	V
V _{OUT(DC)}	Output Voltage Total Variation with Line and Load	$C_{IN} = 10 \mu F \times 3$, $C_{OUT} = 200 \mu F$, $R_{SET} = 40.2 k$ $V_{IN} = 5 V$ to 28V, $I_{OUT} = 0 A$ to 12A (Note 5)	•	1.478	1.5	1.522	V
Input Specification	ons						
V _{IN(UVLO)}	Undervoltage Lockout Threshold	I _{OUT} = 0A			3.2	4	V
I _{INRUSH(VIN)}	Input Inrush Current at Startup	I _{OUT} = 0A. V _{OUT} = 1.5V V _{IN} = 5V V _{IN} = 12V			0.6 0.7		A A
I _{Q(VIN,NO LOAD)}	Input Supply Bias Current	$\begin{aligned} &V_{IN} = 12 \text{V, No Switching} \\ &V_{IN} = 12 \text{V, } V_{OUT} = 1.5 \text{V, Switching Continuous} \\ &V_{IN} = 5 \text{V, No Switching} \\ &V_{IN} = 5 \text{V, } V_{OUT} = 1.5 \text{V, Switching Continuous} \\ &Shutdown, RUN = 0, V_{IN} = 12 \text{V} \end{aligned}$			3.8 38 2.5 42 22		mA mA mA mA
I _{S(VIN)}	Input Supply Current	$V_{IN} = 12V$, $V_{OUT} = 1.5V$, $I_{OUT} = 12A$ $V_{IN} = 12V$, $V_{OUT} = 3.3V$, $I_{OUT} = 12A$ $V_{IN} = 5V$, $V_{OUT} = 1.5V$, $I_{OUT} = 12A$			1.81 3.63 4.29		A A A
INTV _{CC}	V _{IN} = 12V, RUN > 2V	No Load		4.7	5	5.3	V
Output Specificat	tions						
loutdc	Output Continuous Current Range	V _{IN} = 12V, V _{OUT} = 1.5V (Note 5)		0		12	А
$\begin{array}{c} \Delta V_{OUT(LINE)} \\ V_{OUT} \end{array}$	Line Regulation Accuracy	$V_{OUT} = 1.5V$, $I_{OUT} = 0A$, V_{IN} from 4.5V to 28V	•			0.3	%
$\Delta V_{OUT(LOAD)} \ V_{OUT}$	Load Regulation Accuracy	V_{OUT} = 1.5V, I_{OUT} = 0A to 12A, V_{IN} = 12V, with Remote Sense Amplifier (Note 5)	•			0.25	%
V _{OUT(AC)}	Output Ripple Voltage	$I_{OUT} = 0A$, $C_{OUT} = 2 \times 100 \mu F$ X5R Ceramic $V_{IN} = 12 V$, $V_{OUT} = 1.5 V$ $V_{IN} = 5 V$, $V_{OUT} = 1.5 V$			20 18		mV _{P-P}
f _S	Output Ripple Voltage Frequency	$I_{OUT} = 5A$, $V_{IN} = 12V$, $V_{OUT} = 1.5V$			850		kHz
$\Delta V_{OUT(START)}$	Turn-On Overshoot	$ \begin{aligned} &C_{OUT} = 200 \mu F, \ V_{OUT} = 1.5 \text{V}, \ I_{OUT} = 0 \text{A}, \\ &TRACK/SS = 10 \text{nF} \\ &V_{IN} = 12 \text{V} \\ &V_{IN} = 5 \text{V} \end{aligned} $			20 20		mV mV
tstart	Turn-On Time	$C_{OUT} = 200 \mu F$, $V_{OUT} = 1.5 V$, TRACK/SS = Open, $I_{OUT} = 1 A$ Resistive Load $V_{IN} = 12 V$ $V_{IN} = 5 V$			0.5 0.7		ms ms
$\Delta V_{ m OUTLS}$	Peak Deviation for Dynamic Load	Load: 0% to 50% to 0% of Full Load, $C_{OUT} = 2 \times 22 \mu F$ Ceramic, $470 \mu F$ 4V Sanyo POSCAP $V_{IN} = 12 V$ $V_{IN} = 5 V$			35 35		mV mV
t _{SETTLE}	Settling Time for Dynamic Load Step	Load: 0% to 50%, or 50% to 0% of Full Load V _{IN} = 12V			25		μѕ
TOUTPK	Output Current Limit	C _{OUT} = 200µF Ceramic V _{IN} = 12V, V _{OUT} = 1.5V V _{IN} = 5V, V _{OUT} = 1.5V			17 17		A A



ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the specified operating temperature range (Note 2). Otherwise specifications are at $T_A = 25^{\circ}C$, $V_{IN} = 12V$, per typical application (front page) configuration, $R_{SET} = 40.2k$.

SYMBOL	PARAMETER	PARAMETER CONDITIONS		MIN	TYP	MAX	UNITS
Remote Sense Am	p (Note 3)						
V _{OSNS} ⁺ , V _{OSNS} ⁻ CM Range	Common Mode Input Voltage Range	V _{IN} = 12V, RUN > 2V		0		INTV _{CC} – 1	V
DIFFV _{OUT} Range	Output Voltage Range	V _{IN} = 12V, DIFFV _{OUT} Load = 100k		0		INTV _{CC} – 1	V
V _{0S}	Input Offset Voltage Magnitude		•			1.25 2	mV mV
A _V	Differential Gain				1		V/V
GBP	Gain Bandwidth Product				3		MHz
SR	Slew Rate				2		V/µs
R _{IN}	Input Resistance	V _{OSNS} ⁺ to GND			20		kΩ
CMRR	Common Mode Rejection Mode				100		dB
Control Stage							
V_{FB}	Error Amplifier Input Voltage Accuracy	$I_{OUT} = 0A$, $V_{OUT} = 1.5V$	•	0.594	0.6	0.606	V
V _{RUN}	RUN Pin On/Off Threshold			1	1.5	1.9	V
I _{TRACK/SS}	Soft-Start Charging Current	V _{TRACK/SS} = 0V		-1.0	-1.5	-2.0	μA
t _{ON(MIN)}	Minimum On Time	(Note 4)			50	100	ns
t _{OFF(MIN)}	Minimum Off Time	(Note 4)			250	400	ns
R _{PLLIN}	PLLIN Input Resistance				50		kΩ
I _{DRVCC}	Current into DRV _{CC} Pin	V _{OUT} = 1.5V, I _{OUT} = 1A, DRV _{CC} = 5V			18	25	mA
R _{FBHI}	Resistor Between V _{OUT_LCL} and V _{FB}			60.098	60.4	60.702	kΩ
$\overline{V_{MPGM}}$	Margin Reference Voltage				1.18		V
V _{MARG0} , V _{MARG1}	MARG0, MARG1 Voltage Thresholds				1.4		V
PGOOD Output							
ΔV_{FBH}	PGOOD Upper Threshold	V _{FB} Rising		7	10	13	%
ΔV_{FBL}	PGOOD Lower Threshold	V _{FB} Falling		-7	-10	-13	%
$\Delta V_{FB(HYS)}$	PGOOD Hysteresis	V _{FB} Returning			1.5		%
$\overline{V_{PGL}}$	PGOOD Low Voltage	I _{PGOOD} = 5mA			0.15	0.4	V

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: The LTM4601AHV is tested under pulsed load conditions such that $T_J \approx T_A$. The LTM4601AHVE is guaranteed to meet performance specifications from 0°C to 85°C. Specifications over the -40°C to 85°C operating temperature range are assured by design, characterization and correlation with statistical process controls. The LTM4601AHVI is

guaranteed over the -40° C to 85°C operating temperature range. The LTM4601AHVMP is guaranteed and tested over the -55° C to 125°C operating temperature range. For output current derating at high temperature, please refer to Thermal Considerations and Output Current Derating discussion.

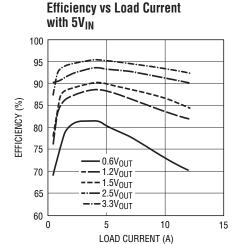
Note 3: Remote sense amplifier recommended for ≤3.3V output.

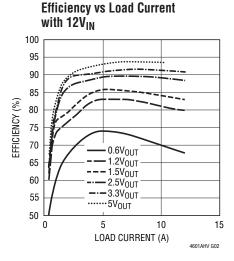
Note 4: 100% tested at wafer level only.

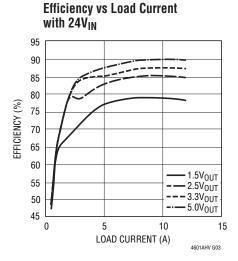
Note 5: See output current derating curves for different $V_{\text{IN}},\,V_{\text{OUT}}$ and $T_{\text{A}}.$

LINEAD TECHNOLOGY

TYPICAL PERFORMANCE CHARACTERISTICS (See Figures 19 and 20 for all curves)

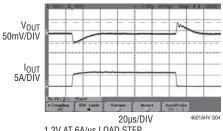






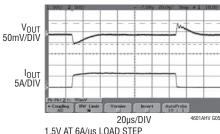
1.2V Transient Response

4601AHV G01



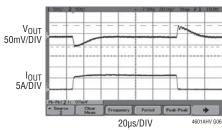
1.2V AT 6A/µs LOAD STEP C_{OUT} = 3× 22µF 6.3V CERAMICS, 470µF 4V SANYO POSCAP C3 = 100pF

1.5V Transient Response



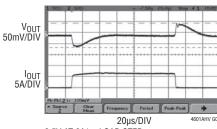
1.5V AT 6A/µs LOAD STEP C_{OUT} = 3× 22µF 6.3V CERAMICS, 470µF 4V SANYO POSCAP C3 = 100pF

1.8V Transient Response



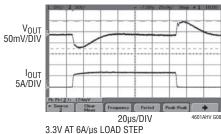
1.8V AT 6A/µs LOAD STEP C_{OUT} = 3× 22µF 6.3V CERAMICS, 470µF 4V SANYO POSCAP C3 = 100pF

2.5V Transient Response



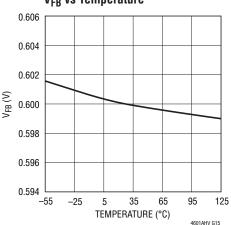
2.5V AT $6A/\mu s$ LOAD STEP $C_{OUT} = 3 \times 22 \mu F$ 6.3V CERAMICS, $470 \mu F$ 4V SANYO POSCAP $C3 = 100 \rho F$

3.3V Transient Response



3.3V AT 6A/µs LOAD STEP C_{OUT} = 3× 22µF 6.3V CERAMICS, 470µF 4V SANYO POSCAP C3 = 100pF

V_{FB} vs Temperature





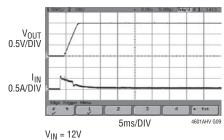
TYPICAL PERFORMANCE CHARACTERISTICS (See Figures 19 and 20 for all curves)

Start-Up, T_A = -55°C

NO LOAD
10A LOAD
10A LOAD
10ms/DIV
4601AHV G16

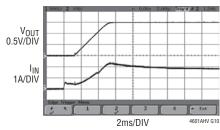
$$\begin{split} &V_{IN}=12V\\ &V_{OUT}=1.5V\\ &C_{OUT}=470\mu\text{F},\,3\times22\mu\text{F}\\ &S0\text{FT-START}=10\text{nF} \end{split}$$





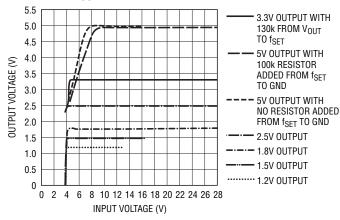
V_{IN} = 12V V_{OUT} = 1.5V C_{OUT} = 470μF, 3× 22μF SOFT-START = 10nF

Start-Up, I_{OUT} = 12A (Resistive Load)

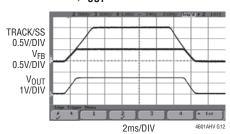


 $V_{\text{IN}} = 12V$ $V_{\text{OUT}} = 1.5V$ $C_{\text{OUT}} = 470 \mu \text{F}, 3 \times 22 \mu \text{F}$ SOFT-START = 10 nF

VIN to VOUT Step-Down Ratio

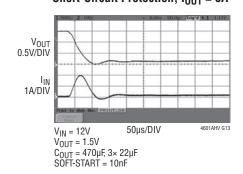


Track, I_{OUT} = 12A

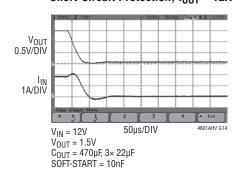


$$\begin{split} &V_{IN}=12V\\ &V_{OUT}=1.5V\\ &C_{OUT}=470\mu\text{F}, \, 3\times 22\mu\text{F}\\ &SOFT\text{-START}=10\text{nF} \end{split}$$

Short-Circuit Protection, $I_{OUT} = 0A$



Short-Circuit Protection, I_{OUT} = 12A





PIN FUNCTIONS (See Package Description for Pin Assignment)

 V_{IN} (Bank 1): Power Input Pins. Apply input voltage between these pins and PGND pins. Recommend placing input decoupling capacitance directly between V_{IN} pins and PGND pins.

V_{OUT} (**Bank 3**): Power Output Pins. Apply output load between these pins and PGND pins. Recommend placing output decoupling capacitance directly between these pins and PGND pins. See Figure 17.

PGND (Bank 2): Power ground pins for both input and output returns.

V_{OSNS}⁻ (**Pin M12**): (–) Input to the Remote Sense Amplifier. This pin connects to the ground remote sense point. The remote sense amplifier is used for $V_{OUT} \le 3.3V$. Tie to INTV_{CC} if not used.

 V_{OSNS}^+ (Pin J12): (+) Input to the Remote Sense Amplifier. This pin connects to the output remote sense point. The remote sense amplifier is used for $V_{OUT} \le 3.3$ V. Tie to GND if not used.

DIFFV_{OUT} (**Pin K12**): Output of the Remote Sense Amplifier. This pin connects to the V_{OUT_LCL} pin. Leave floating if remote sense amplifier is not used.

DRV_{CC} (**Pin E12**): This pin normally connects to INTV_{CC} for powering the internal MOSFET drivers. This pin can be biased up to 6V from an external supply with about 50mA capability, or an external circuit shown in Figure 18. This improves efficiency at the higher input voltages by reducing power dissipation in the module.

INTV_{CC} (Pin A7, D9): This pin is for additional decoupling of the 5V internal regulator. These pins are internally connected. Pin A7 is a test pin.

PLLIN (Pin A8): External Clock Synchronization Input to the Phase Detector. This pin is internally terminated to SGND with a 50k resistor. Apply a clock with high level above 2V and below $INTV_{CC}$. See Applications Information.

TRACK/SS (Pin A9): Output Voltage Tracking and Soft-Start Pin. When the module is configured as a master output, then a soft-start capacitor is placed on this pin to ground to control the master ramp rate. A soft-start capacitor can be used for soft-start turn on as a stand alone regulator. Slave operation is performed by putting a resistor divider from the master output to ground, and connecting the center point of the divider to this pin. See Applications Information.

MPGM (Pins A12, B11): Programmable Margining Input. A resistor from this pin to ground sets a current that is equal to 1.18V/R. This current multiplied by $10k\Omega$ will equal a value in millivolts that is a percentage of the 0.6V reference voltage. See Applications Information. To parallel LTM4601AHVs, each requires an individual MPGM resistor. Do not tie MPGM pins together. Both pins are internally connected. Pin A12 is a test pin.

f_{SET} (Pins B12, C11): Frequency Set Internally to 850kHz. An external resistor can be placed from this pin to ground to increase frequency. See Applications Information for frequency adjustment. Both pins are internally connected. Pin B12 is a test pin.

 V_{FB} (Pin F12): The Negative Input of the Error Amplifier. Internally, this pin is connected to V_{OUT_LCL} pin with a 60.4k precision resistor. Different output voltages can be programmed with an additional resistor between V_{FB} and SGND pins. See Applications Information.

MARGO (Pin C12): This pin is the LSB logic input for the margining function. Together with the MARG1 pin it will determine if margin high, margin low or no margin state is applied. The pin has an internal pull-down resistor of 50k. See Applications Information.

MARG1 (Pin D12): This pin is the MSB logic input for the margining function. Together with the MARGO pin it will determine if margin high, margin low or no margin state is applied. The pin has an internal pull-down resistor of 50k. See Applications Information.

SGND (Pins H12, H11, G11): Signal Ground. These pins connect to PGND at output capacitor point. See Figure 17.



PIN FUNCTIONS (See Package Description for Pin Assignment)

COMP (Pin A11): Current Control Threshold and Error Amplifier Compensation Point. The current comparator threshold increases with this control voltage. The voltage ranges from 0V to 2.4V with 0.7V corresponding to zero sense voltage (zero current).

PGOOD (Pins G12, F11): Output Voltage Power Good Indicator. Open-drain logic output that is pulled to ground when the output voltage is not within $\pm 10\%$ of the regulation point, after a 25 μ s power bad mask timer expires.

RUN (Pin A10): Run Control Pin. A voltage above 1.9V will turn on the module, and when below 1V, will turn

off the module. A programmable UVLO function can be accomplished by connecting to a resistor divider from V_{IN} to ground. See Figure 1. This pin has a 5.1V Zener to ground. Maximum pin voltage is 5V. Limit current into the RUN pin to less than 1mA.

V_{OUT_LCL} (**Pin L12**): V_{OUT} connects directly to this pin to bypass the remote sense amplifier, or DIFFV_{OUT} connects to this pin when the remote sense amplifier is used.

MTP1, MTP2, MPT3 (Pins C10, D10, D11): Extra Mounting Pads. These pads must be left floating (electrical open circuit) and are used for enhanced solder joint strength.

SIMPLIFIED BLOCK DIAGRAM

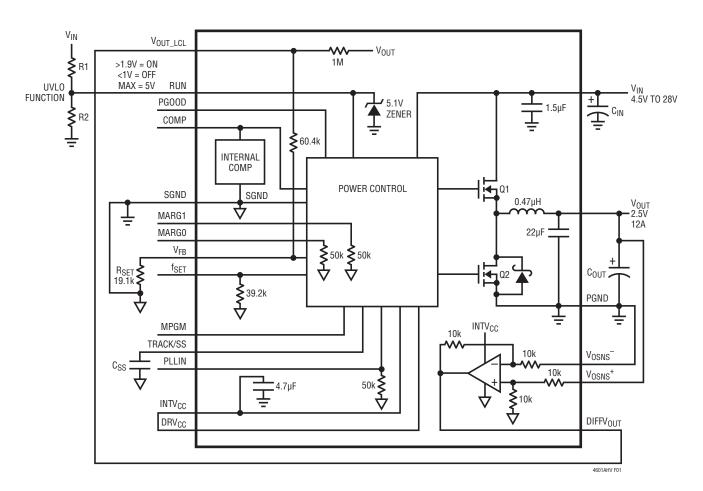


Figure 1. Simplified LTM4601AHV Block Diagram



DECOUPLING REQUIREMENTS

_						
$T_{\Lambda} = 25^{\circ}C$	VIN =	12V	llse	Figure	1 c	onfiguration.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
C _{IN}	External Input Capacitor Requirement (V _{IN} = 4.5V to 28V, V _{OUT} = 2.5V)	I _{OUT} = 12A	20	30		μF
C _{OUT}	External Output Capacitor Requirement (V _{IN} = 4.5V to 28V, V _{OUT} = 2.5V)	I _{OUT} = 12A	100	200		μF

OPERATION

Power Module Description

The LTM4601AHV is a standalone nonisolated switching mode DC/DC power supply. It can deliver up to 12A of DC output current with some external input and output capacitors. This module provides precisely regulated output voltage programmable via one external resistor from $0.6 V_{DC}$ to $5.0 V_{DC}$ over a 4.5V to 28V wide input voltage. Typical application schematics are shown in Figures 19 and 20.

The LTM4601AHV has an integrated constant on-time current mode regulator, ultralow $R_{DS(0N)}$ FETs with fast switching speed and integrated Schottky diodes. The typical switching frequency is 850kHz at full load. With current mode control and internal feedback loop compensation, the LTM4601AHV module has sufficient stability margins and good transient performance under a wide range of operating conditions and with a wide range of output capacitors, even all ceramic output capacitors.

Current mode control provides cycle-by-cycle fast current limit. Besides, foldback current limiting is provided in an overcurrent condition while V_{FB} drops. Internal overvoltage and undervoltage comparators pull the open-drain PGOOD output low if the output feedback voltage exits a $\pm 10\%$ window around the regulation point. Furthermore,

in an overvoltage condition, internal top FET Q1 is turned off and bottom FET Q2 is turned on and held on until the overvoltage condition clears.

Pulling the RUN pin below 1V forces the controller into its shutdown state, turning off both Q1 and Q2. At low load current, the module works in continuous current mode by default to achieve minimum output ripple voltage.

When DRV_{CC} pin is connected to $INTV_{CC}$ an integrated 5V linear regulator powers the internal gate drivers. If a 5V external bias supply is applied on the DRV_{CC} pin, then an efficiency improvement will occur due to the reduced power loss in the internal linear regulator. This is especially true at the high end of the input voltage range.

The LTM4601AHV has a very accurate differential remote sense amplifier with very low offset. This provides for very accurate output voltage measurement at the load. The MPGM pin, MARGO pin and MARG1 pin are used to support voltage margining, where the percentage of margin is programmed by the MPGM pin, and the MARGO and MARG1 select margining.

The PLLIN pin provides frequency synchronization of the device to an external clock. The TRACK/SS pin is used for power supply tracking and soft-start programming.



The typical LTM4601AHV application circuits are shown in Figures 19 and 20. External component selection is primarily determined by the maximum load current and output voltage. Refer to Table 2 for specific external capacitor requirements for a particular application.

VIN to VOLIT Step-Down Ratios

There are restrictions in the maximum V_{IN} and V_{OUT} step down ratio that can be achieved for a given input voltage. These constraints are shown in the Typical Performance Characteristics curves labeled " V_{IN} to V_{OUT} Step-Down Ratio". Note that additional thermal derating may apply. See the Thermal Considerations and Output Current Derating section of this data sheet.

Output Voltage Programming and Margining

The PWM controller has an internal 0.6V reference voltage. As shown in the Block Diagram, a 1M and a 60.4k 0.5% internal feedback resistor connects V_{OUT} and V_{FB} pins together. The V_{OUT_LCL} pin is connected between the 1M and the 60.4k resistor. The 1M resistor is used to protect against an output overvoltage condition if the V_{OUT_LCL} pin is not connected to the output, or if the remote sense amplifier output is not connected to V_{OUT_LCL} . In these cases, the output voltage will default to 0.6V. Adding a resistor R_{SET} from the V_{FB} pin to SGND pin programs the output voltage:

$$V_{OUT} = 0.6V \frac{60.4k + R_{SET}}{R_{SET}}$$

or equivalently:

$$R_{SET} = \frac{60.4k}{\left(\frac{V_{OUT}}{0.6V} - 1\right)}$$

Table 1. Standard 1% Resistor Values

R_{SET} (k Ω)	Open	60.4	40.2	30.1	25.5	19.1	13.3	8.25
V _{OUT} (V)	0.6	1.2	1.5	1.8	2	2.5	3.3	5

The MPGM pin programs a current that when multiplied by an internal 10k resistor sets up the 0.6V reference \pm offset for margining. A 1.18V reference divided by the R_{PGM} resistor on the MPGM pin programs the current. Calculate V_{OUT(MARGIN)}:

$$V_{OUT(MARGIN)} = \frac{\%V_{OUT}}{100} \cdot V_{OUT}$$

where $%V_{OUT}$ is the percentage of V_{OUT} you want to margin, and $V_{OUT(MARGIN)}$ is the margin quantity in volts:

$$R_{PGM} = \frac{V_{OUT}}{0.6V} \cdot \frac{1.18V}{V_{OUT(MARGIN)}} \cdot 10k$$

where R_{PGM} is the resistor value to place on the MPGM pin to ground.

The margining voltage, $V_{OUT(MARGIN)}$, will be added or subtracted from the nominal output voltage as determined by the state of the MARGO and MARG1 pins. See the truth table below:

MARG1	MARGO	MODE
LOW	LOW	NO MARGIN
LOW	HIGH	MARGIN UP
HIGH	LOW	MARGIN DOWN
HIGH	HIGH	NO MARGIN

Input Capacitors

LTM4601AHV module should be connected to a low AC impedance DC source. Input capacitors are required to be placed adjacent to the module. In Figure 20, the $10\mu\text{F}$ ceramic input capacitors are selected for their ability to handle the large RMS current into the converter. An input bulk capacitor of $100\mu\text{F}$ is optional. This $100\mu\text{F}$ capacitor is only needed if the input source impedance is compromised by long inductive leads or traces.



For a buck converter, the switching duty cycle can be estimated as:

$$D = \frac{V_{OUT}}{V_{IN}}$$

Without considering the inductor ripple current, the RMS current of the input capacitor can be estimated as:

$$I_{\text{CIN(RMS)}} = \frac{I_{\text{OUT(MAX)}}}{\eta\%} \bullet \sqrt{D \bullet (1-D)}$$

In the above equation, $\eta\%$ is the estimated efficiency of the power module. C_{IN} can be a switcher-rated electrolytic aluminum capacitor, OS-CON capacitor or high value ceramic capacitor. Note the capacitor ripple current ratings are often based on temperature and hours of life. This makes it advisable to properly derate the input capacitor, or choose a capacitor rated at a higher temperature than required. Always contact the capacitor manufacturer for derating requirements.

In Figures 19 and 20, the 10µF ceramic capacitors are together used as a high frequency input decoupling capacitor. In a typical 12A output application, three very low ESR, X5R or X7R 10µF ceramic capacitors are recommended. These decoupling capacitors should be placed directly adjacent to the module input pins in the PCB layout to minimize the trace inductance and high frequency AC noise. Each 10µF ceramic is typically good for 2A to 3A of RMS ripple current. Refer to your ceramics capacitor catalog for the RMS current ratings.

Multiphase operation with multiple LTM4601AHV devices in parallel will lower the effective input RMS ripple current due to the interleaving operation of the regulators. Application Note 77 provides a detailed explanation. Refer to Figure 2 for the input capacitor ripple current reduction as a function of the number of phases. The figure provides a ratio of RMS ripple current to DC load current as function of duty cycle and the number of paralleled phases.

Pick the corresponding duty cycle and the number of phases to arrive at the correct ripple current value. For example, the 2-phase parallel LTM4601AHV design provides 24A at 2.5V output from a 12V input. The duty cycle is DC = 2.5V/12V = 0.21. The 2-phase curve has a ratio of ~ 0.25 for a duty cycle of 0.21. This 0.25 ratio of RMS ripple current to a DC load current of 24A equals $\sim 6A$ of input RMS ripple current for the external input capacitors.

Output Capacitors

The LTM4601AHV is designed for low output ripple voltage. The bulk output capacitors defined as C_{OUT} are chosen with low enough effective series resistance (ESR) to meet the output ripple voltage and transient requirements. C_{OUT} can be a low ESR tantalum capacitor, a low ESR polymer capacitor or a ceramic capacitor. The typical capacitance is $200\mu F$ if all ceramic output capacitors are used. Additional output filtering may be required by the system designer if further reduction of output ripple or dynamic transient spikes is required. Table 2 shows a matrix of different output voltages and output capacitors to minimize the voltage droop and overshoot during a $5A/\mu S$ transient. The table optimizes total equivalent ESR and total bulk capacitance to maximize transient performance.

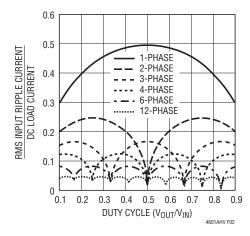


Figure 2. Normalized Input RMS Ripple Current vs Duty Cycle for One to Six Modules (Phases)



Multiphase operation with multiple LTM4601AHV devices in parallel will lower the effective output ripple current due to the interleaving operation of the regulators. For example, each LTM4601AHV's inductor current in a 12V to 2.5V multiphase design can be read from the Inductor Ripple

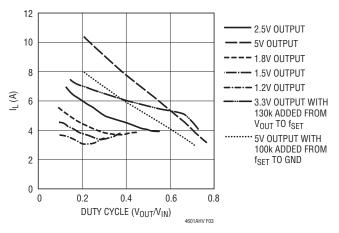


Figure 3. Inductor Ripple Current vs Duty Cycle

Current versus Duty Cycle graph (Figure 3). The large ripple current at low duty cycle and high output voltage can be reduced by adding an external resistor from f_{SET} to ground which increases the frequency. If the duty cycle is DC = 2.5V/12V = 0.21, the inductor ripple current for 2.5V output at 21% duty cycle is ~6A in Figure 3.

Figure 4 provides a ratio of peak-to-peak output ripple current to the inductor current as a function of duty cycle and the number of paralleled phases. Pick the corresponding duty cycle and the number of phases to arrive at the correct output ripple current ratio value. If a 2-phase operation is chosen at a duty cycle of 21%, then 0.6 is the ratio. This 0.6 ratio of output ripple current to inductor ripple of 6A equals 3.6A of effective output ripple current. Refer to Application Note 77 for a detailed explanation of output ripple current reduction as a function of paralleled phases.

The output ripple voltage has two components that are related to the amount of bulk capacitance and effective series resistance (ESR) of the output bulk capacitance.

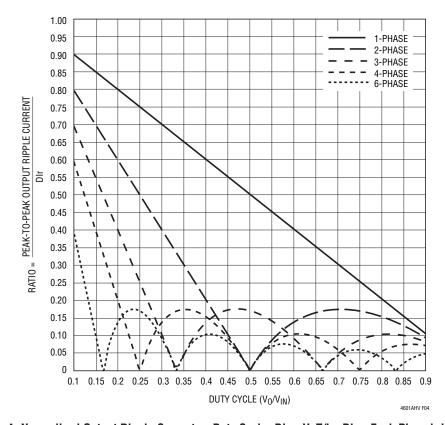


Figure 4. Normalized Output Ripple Current vs Duty Cycle, $DIr = V_0T/L_1$, DIr = Each Phase's Inductor Current

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Therefore, the output ripple voltage can be calculated with the known effective output ripple current. The equation: $\Delta V_{OUT(P-P)} \approx (\Delta I_L/(8 \bullet f \bullet m \bullet C_{OUT}) + ESR \bullet \Delta I_L), \text{ where } f \text{ is frequency and } m \text{ is the number of parallel phases. This calculation process can be easily accomplished by using LTpowerCADTM.}$

Fault Conditions: Current Limit and Overcurrent Foldback

LTM4601AHV has a current mode controller, which inherently limits the cycle-by-cycle inductor current not only in steady-state operation, but also in response to transients.

To further limit current in the event of an overload condition, the LTM4601AHV provides foldback current limiting. If the output voltage falls by more than 50%, then the maximum output current is progressively lowered to about one sixth of its full current limit value. The current limit returns to its nominal value once V_{OUT} and V_{FB} have returned to their nominal values.

Soft-Start and Tracking

The TRACK/SS pin provides a means to either soft-start the regulator or track it to a different power supply. A capacitor on this pin will program the ramp rate of the output voltage. A 1.5µA current source will charge up the external soft-start capacitor to 80% of the 0.6V internal voltage reference plus or minus any margin delta. This will control the ramp of the internal reference and the output voltage. The total soft-start time can be calculated as:

$$t_{SOFTSTART} = 0.8 \cdot (0.6V \pm V_{OUT(MARGIN)}) \cdot \frac{C_{SS}}{1.5 \mu A}$$

When the RUN pin falls below 1.5V, then the TRACK/SS pin is reset to allow for proper soft-start control when the regulator is enabled again. Current foldback and forced continuous mode are disabled during the soft-start process. The soft-start function can also be used to control the output ramp up time, so that another regulator can be easily tracked to it.

Output Voltage Tracking

Output voltage tracking can be programmed externally using the TRACK/SS pin. The output can be tracked up and down with another regulator. The master regulator's output is divided down with an external resistor divider that is the same as the slave regulator's feedback divider. Figure 5 shows an example of coincident tracking. Ratiometric modes of tracking can be achieved by selecting different resistor values to change the output tracking ratio. The master output must be greater than the slave output for the tracking to work. Figure 6 shows the coincident output tracking characteristics.

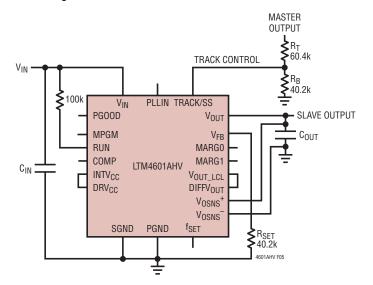


Figure 5. Coincident Tracking Schematic

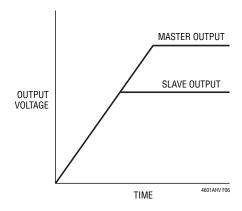


Figure 6. Coincident Output Tracking Characteristics



Run Enable

The RUN pin is used to enable the power module. The pin has an internal 5.1V Zener to ground. The pin can be driven with a logic input not to exceed 5V.

The RUN pin can also be used as an undervoltage lock out (UVLO) function by connecting a resistor divider from the input supply to the RUN pin:

$$V_{UVLO} = \frac{R1 + R2}{R2} \bullet 1.5V$$

See Figure 1, Simplified Block Diagram.

Power Good

The PGOOD pin is an open-drain pin that can be used to monitor valid output voltage regulation. This pin monitors a $\pm 10\%$ window around the regulation point and tracks with margining.

COMP Pin

This pin is the external compensation pin. The module has already been internally compensated for most output voltages. Table 2 is provided for most application requirements. LTpowerCAD is available for other control loop optimization.

PLLIN

The power module has a phase-locked loop comprised of an internal voltage controlled oscillator and a phase detector. This allows the internal top MOSFET turn-on to be locked to the rising edge of an external clock. The frequency range is ±30% around the operating frequency of 850kHz. A pulse detection circuit is used to detect a clock on the PLLIN pin to turn on the phase-locked loop. The pulse width of the clock has to be at least 400ns and the amplitude at least 2V. The PLLIN pin must be driven from a low impedance source such as a logic gate located close to the pin. During start-up of the regulator, the phase-locked loop function is disabled.

INTV_{CC} and DRV_{CC} Connection

An internal low dropout regulator produces an internal 5V supply that powers the control circuitry and DRV $_{CC}$ for driving the internal power MOSFETs. Therefore, if the system does not have a 5V power rail, the LTM4601AHV can be directly powered by V_{IN} . The gate drive current through the LDO is about 20mA. The internal LDO power dissipation can be calculated as:

$$P_{LDO\ LOSS} = 20 \text{mA} \cdot (V_{IN} - 5V)$$

The LTM4601AHV also provides the external gate drive voltage pin DRV $_{CC}$. If there is a 5V rail in the system, it is recommended to connect the DRV $_{CC}$ pin to the external 5V rail. This is especially true for higher input voltages. Do not apply more than 6V to the DRV $_{CC}$ pin. A 5V output can be used to power the DRV $_{CC}$ pin with an external circuit as shown in Figure 18.

Parallel Operation of the Module

The LTM4601AHV device is an inherently current mode controlled device. Parallel modules will have very good current sharing. This will balance the thermals on the design. Figure 21 shows the schematic of a parallel design. The voltage feedback equation changes with the variable n as modules are paralleled:

$$V_{OUT} = 0.6V \frac{\frac{60.4k}{N} + R_{SET}}{R_{SET}}$$

or equivalently:

$$R_{SET} = \frac{\frac{60.4k}{N}}{\left(\frac{V_{OUT}}{0.6V} - 1\right)}$$

where N is the number of paralleled modules.

Figure 21 shows two LTM4601AHV modules used in a parallel design. An LTM4601AHV device can be used without the differential amplifier.

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Thermal Considerations and Output Current Derating

The power loss curves in Figures 7 and 8 can be used in coordination with the load current derating curves in Figures 9 to 16 for calculating an approximate θ_{JA} for the module with various heat sinking methods. Thermal models are derived from several temperature measurements at the bench and thermal modeling analysis. Thermal Application Note 103 provides a detailed explanation of the analysis for the thermal models and the derating curves. Tables 3 and 4 provide a summary of the equivalent θ_{JA} for the noted

conditions. These equivalent θ_{JA} parameters are correlated to the measured values, and are improved with air flow. The case temperature is maintained at 100°C or below for the derating curves. The maximum case temperature of 100°C is to allow for a rise of about 13°C to 25°C inside the μ Module regulator with a thermal resistance θ_{JC} from junction to case between 6°C/W to 9°C/W. This will maintain the maximum junction temperature inside the device below 125°C.

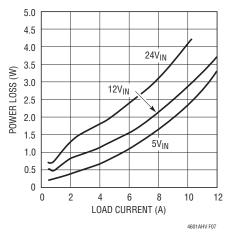


Figure 7. 1.5V Output Power Loss

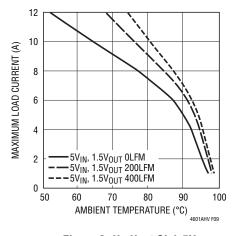


Figure 9. No Heat Sink 5VIN

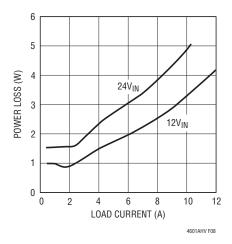


Figure 8. 3.3V Output Power Loss

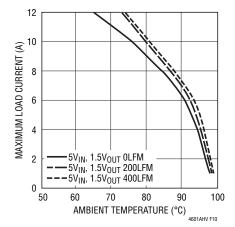


Figure 10. BGA Heat Sink 5V_{IN}



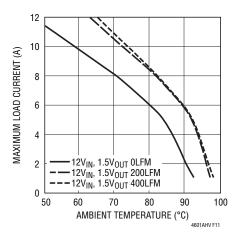


Figure 11. No Heat Sink 12V_{IN}

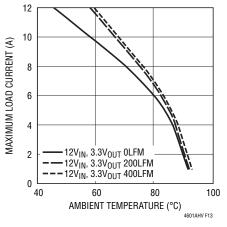


Figure 13. 12V_{IN}, 3.3V_{OUT}, No Heat Sink

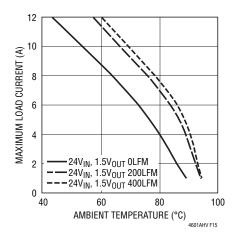


Figure 15. $24V_{IN}$, $1.5V_{OUT}$, No Heat Sink

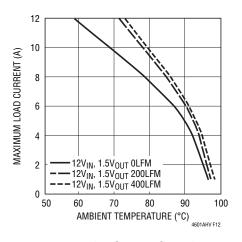


Figure 12. BGA Heat Sink 12V_{IN}

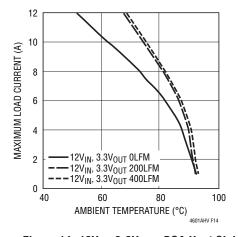


Figure 14. 12V_{IN}, 3.3V_{OUT}, BGA Heat Sink

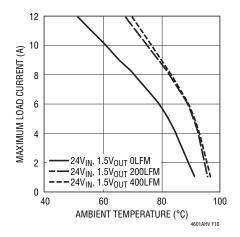


Figure 16. $24V_{IN}$, $1.5V_{OUT}$, BGA Heat Sink

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Table 2. Output Voltage Response Versus Component Matrix* (Refer to Figures 19 and 20), OA to 6A Load Step

TYPICAL MEASURED VALUES

C _{OUT1} VENDORS	PART NUMBER	C _{OUT2} VENDORS	PART NUMBER
TDK	C4532X5R0J107MZ (100µF, 6.3V)	SANYO POSCAP	6TPE330MIL (330μF, 6.3V)
TAIYO YUDEN	JMK432BJ107MU-T (100μF, 6.3V)	SANYO POSCAP	2R5TPE470M9 (470μF, 2.5V)
TAIYO YUDEN	JMK316BJ226ML-T501 (22μF, 6.3V)	SANYO POSCAP	4TPE470MCL (470μF, 4V)

V _{OUT} (V)	C _{IN} (CERAMIC)	C _{IN} (BULK)	C _{OUT1} (CERAMIC)	C _{OUT2} (BULK)	C _{COMP}	C3	V _{IN} (V)	DROOP (mV)	PEAK TO PEAK (mV)	RECOVERY TIME (µs)	LOAD STEP (A/µs)	R_{SET} ($k\Omega$)
1.2	$2 \times 10 \mu F 35V$	150μF 35V	3 × 22μF 6.3V	470μF 4V	NONE	47pF	5	70	140	30	6	60.4
1.2	$2\times10\mu F~35V$	150μF 35V	1 × 100µF 6.3V	470µF 2.5V	NONE	100pF	5	35	70	20	6	60.4
1.2	$2\times 10 \mu F~35 V$	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	22pF	5	70	140	20	6	60.4
1.2	$2 \times 10 \mu F 35V$	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	5	40	93	30	6	60.4
1.2	2 × 10µF 35V	150µF 35V	3 × 22μF 6.3V	470μF 4V	NONE	100pF	12	70	140	30	6	60.4
1.2	2 × 10µF 35V	150µF 35V	1 × 100µF 6.3V	470μF 2.5V	NONE	100pF	12	35	70	20	6	60.4
1.2	2 × 10µF 35V	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	22pF	12	70	140	20	6	60.4
1.2	2 × 10µF 35V	150µF 35V	4 × 100µF 6.3V	NONE	NONE	100pF	12	49	98	20	6	60.4
1.5	2 × 10μF 35V	150μF 35V	3 × 22μF 6.3V	470μF 4V	NONE	100pF	5	48	100	35	6	40.2
1.5	2 × 10μF 35V	150μF 35V	1 × 100µF 6.3V	470μF 2.5V	NONE	33pF	5	54	109	30	6	40.2
1.5	2 × 10µF 35V	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	100pF	5	44	84	30	6	40.2
1.5	2 × 10µF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	5	61	118	30	6	40.2
1.5	2 × 10μF 35V	150μF 35V	3 × 22μF 6.3V	470µF 4V	NONE	100pF	12	48	100	35	6	40.2
1.5	2 × 10μF 35V	150μF 35V	1 × 100µF 6.3V	470μF 2.5V	NONE	33pF	12	54	109	30	6	40.2
1.5	2 × 10μF 35V	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	100pF	12	44	89	25	6	40.2
1.5	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	12	54	108	25	6	40.2
1.8	2 × 10μF 35V	150μF 35V	3 × 22μF 6.3V	470μF 4V	NONE	47pF	5	48	100	30	6	30.1
1.8	2 × 10μF 35V	150µF 35V	1 × 100µF 6.3V	470μF 2.5V	NONE	100pF	5	44	90	20	6	30.1
1.8	2 × 10μF 35V	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	100pF	5	68	140	30	6	30.1
1.8	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	5	65	130	30	6	30.1
1.8	2 × 10μF 35V	150µF 35V	3 × 22μF 6.3V	470μF 4V	NONE	100pF	12	60	120	30	6	30.1
1.8	2 × 10μF 35V	150µF 35V	1 × 100µF 6.3V	470μF 2.5V	NONE	100pF	12	60	120	30	6	30.1
1.8	2 × 10μF 35V	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	100pF	12	68	140	30	6	30.1
1.8	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	12	65	130	20	6	30.1
2.5	2 × 10μF 35V	150µF 35V	1 × 100µF 6.3V	470μF 4V	NONE	100pF	5	48	103	30	6	19.1
2.5	2 × 10μF 35V	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	220pF	5	56	113	30	6	19.1
2.5	$2 \times 10 \mu F 35V$	150μF 35V	3 × 22μF 6.3V	470μF 4V	NONE	NONE	5	57	116	30	6	19.1
2.5	$2 \times 10 \mu F 35V$	150μF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	5	60	115	25	6	19.1
2.5	$2 \times 10 \mu F 35V$	150µF 35V	1 × 100µF 6.3V	470μF 4V	NONE	100pF	12	48	103	30	6	19.1
2.5	$2 \times 10 \mu F 35V$	150µF 35V	3 × 22μF 6.3V	470μF 4V	NONE	NONE	12	51	102	30	6	19.1
2.5	$2 \times 10 \mu F 35V$	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	220pF	12	56	113	30	6	19.1
2.5	$2 \times 10 \mu F 35V$	150µF 35V	4 × 100μF 6.3V	NONE	NONE	220pF	12	70	140	25	6	19.1
3.3	$2 \times 10 \mu F 35V$	150µF 35V	2 × 100µF 6.3V	330µF 6.3V	NONE	100pF	7	120	240	30	6	13.3
3.3	$2 \times 10 \mu F 35V$	150µF 35V	1 × 100µF 6.3V	470μF 4V	NONE	100pF	7	110	214	30	6	13.3
3.3	$2 \times 10 \mu F 35V$	150μF 35V	3 × 22μF 6.3V	470μF 4V	NONE	100pF	7	110	214	30	6	13.3
3.3	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	7	114	230	30	6	13.3
3.3	2 × 10μF 35V	150µF 35V	1 × 100μF 6.3V	470μF 4V	NONE	100pF	12	110	214	30	6	13.3
3.3	2 × 10μF 35V	150µF 35V	3 × 22μF 6.3V	470μF 4V	NONE	150pF	12	110	214	35	6	13.3
3.3	2 × 10μF 35V	150µF 35V	2 × 100μF 6.3V	330µF 6.3V	NONE	100pF	12	110	214	35	6	13.3
3.3	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	100pF	12	114	230	30	6	13.3
5	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	22pF	15	188	375	25	6	8.25
5	2 × 10μF 35V	150µF 35V	4 × 100μF 6.3V	NONE	NONE	22pF	20	159	320	25	6	8.25

^{*}X7R is recommended for extended temperature range



Table 3. 1.5V Output at 12A

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W) LGA	θ _{JA} (°C/W) BGA
Figures 9, 11, 15	5, 12, 24	Figure 7	0	None	15.2	15.7
Figures 9, 11, 15	5, 12, 24	Figure 7	200	None	14	14.5
Figures 9, 11, 15	5, 12, 24	Figure 7	400	None	12	12.5
Figures 10, 12, 16	5, 12, 24	Figure 7	0	BGA Heat Sink	13.9	14.4
Figures 10, 12, 16	5, 12, 24	Figure 7	200	BGA Heat Sink	11.3	11.8
Figures 10, 12, 16	5, 12, 24	Figure 7	400	BGA Heat Sink	10.25	10.75

Table 4. 3.3V Output at 12A

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W) LGA	θ _{JA} (°C/W) BGA
Figure 13	12	Figure 8	0	None	15.2	15.7
Figure 13	12	Figure 8	200	None	14.6	15.0
Figure 13	12	Figure 8	400	None	13.4	13.9
Figure 14	12	Figure 8	0	BGA Heat Sink	13.9	14.4
Figure 14	12	Figure 8	200	BGA Heat Sink	11.1	11.6
Figure 14	12	Figure 8	400	BGA Heat Sink	10.5	11

Heat Sink Manufacturer

Aavid Thermalloy	Part No: 375424B00034G	Phone: 603-224-9988
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Safety Considerations

The LTM4601AHV modules do not provide isolation from V_{IN} to V_{OUT} . There is no internal fuse. If required, a slow blow fuse with a rating twice the maximum input current needs to be provided to protect each unit from catastrophic failure.

Layout Checklist/Example

The high integration of LTM4601AHV makes the PCB board layout very simple and easy. However, to optimize its electrical and thermal performance, some layout considerations are still necessary.

- Use large PCB copper areas for high current path, including V_{IN}, PGND and V_{OUT}. It helps to minimize the PCB conduction loss and thermal stress.
- Place high frequency ceramic input and output capacitors next to the V_{IN}, PGND and V_{OUT} pins to minimize high frequency noise.
- Place a dedicated power ground layer underneath the unit. Refer frequency synchronization source to power ground.

- To minimize the via conduction loss and reduce module thermal stress, use multiple vias for interconnection between top layer and other power layers.
- Do not put vias directly on pads unless they are capped.
- Use a separated SGND ground copper area for components connected to signal pins. Connect the SGND to PGND underneath the unit.

Figure 17 gives a good example of the recommended layout.

Frequency Adjustment

The LTM4601AHV is designed to typically operate at 850kHz across most input conditions. The f_{SET} pin is normally left open. The switching frequency has been optimized for maintaining constant output ripple noise over most operating ranges. The 850kHz switching frequency and the 400ns minimum off time can limit operation at higher duty cycles like 5V to 3.3V, and produce excessive inductor ripple currents for lower duty cycle applications like 28V to 5V. The $5V_{OUT}$ and $3.3V_{OUT}$ drop out curves are modified by adding an external resistor on the f_{SET} pin to allow for lower input voltage operation, or higher input voltage operation.

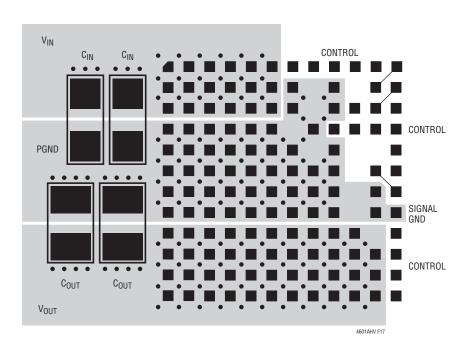


Figure 17. Recommended Layout (LGA and BGA PCB Layouts Are Identical with the Exception of Circle Pads for BGA. See Package Description.)



Example for 5V Output

LTM4601AHV minimum on-time = 100ns $t_{ON} = [(V_{OUT} \cdot 10pF)/I_{fSET}]$, for $V_{OUT} > 4.8V$ use 4.8V

LTM4601AHV minimum off-time = 400ns

 $t_{OFF} = t - t_{ON}$, where t = 1/Frequency

Duty Cycle = t_{ON}/t or V_{OUT}/V_{IN}

Equations for setting frequency:

 $I_{fSFT} = [V_{IN}/(3 \cdot R_{fSFT})]$, for 28V operation, $I_{fSFT} = 238\mu A$, $t_{ON} = [(4.8 \cdot 10pF)/l_{fSET}], t_{ON} = 202ns, where the internal$ R_{fSET} is 39.2k. Frequency = $[V_{OUT}/(V_{IN} \cdot t_{ON})] = [5V/(28 \cdot t_{ON})]$ 202ns)] ~ 884kHz. The inductor ripple current begins to get high at the higher input voltages due to a larger voltage across the inductor. This is noted in the Inductor Ripple Current vs Duty Cycle graph (Figure 3) where $I_1 \approx 10A$ at 20% duty cycle. The inductor ripple current can be lowered at the higher input voltages by adding an external resistor from f_{SFT} to ground to increase the switching frequency. A 7A ripple current is chosen, and the total peak current is equal to 1/2 of the 7A ripple current plus the output current. The 5V output current is limited to 8A, so the total peak current is less than 11.5A. This is below the 14A peak specified value. A 100k resistor is placed from f_{SFT} to ground, and the parallel combination of 100k and 39.2k equates to 28k. The IfSET calculation with 28k and 28V input voltage equals $333\mu A$. This equates to a t_{ON} of 144ns. This will increase the switching frequency from ~884kHz to ~1.24MHz for the 28V to 5V conversion. The minimum on time is above 100ns at 28V input. Since the switching frequency is approximately constant over input and output conditions, then the lower input voltage range is limited to 10V for the 1.24MHz operation due to the 400ns minimum off time. Equation: $t_{ON} = (V_{OUT}/V_{IN}) \cdot (1/V_{IN}) \cdot (1/V_{$ Frequency) equates to a 400ns on time, and a 400ns off time. The V_{IN} to V_{OUT} Step-Down Ratio curves reflect an operating range of 10V to 28V for 1.24MHz operation with a 100k resistor to ground as shown in Figure 18, and an 8V to 16V operation for f_{SET} floating. These modifications are made to provide wider input voltage ranges for the 5V output designs while limiting the inductor ripple current, and maintaining the 400ns minimum off-time.

Example for 3.3V Output

LTM4601AHV minimum on-time = 100ns $t_{ON} = [(V_{OUT} \cdot 10pF)/I_{fSET}]$

LTM4601AHV minimum off-time = 400ns $t_{OFF} = t - t_{ON}$, where t = 1/Frequency

Duty Cycle (DC) = t_{ON}/t or V_{OUT}/V_{IN}

Equations for setting frequency:

 $I_{fSET} = [V_{IN}/(3 • R_{fSET})]$, for 28V operation, $I_{fSET} = 238\mu A$, $t_{ON} = [(3.3 • 10pF)/I_{fSET}]$, $t_{ON} = 138.7ns$, where the internal R_{fSET} is 39.2k. Frequency = $[V_{OUT}/(V_{IN} • t_{ON})] = [3.3V/(28 • 138.7ns)] \sim 850kHz$. The minimum on-time and minimum off-time are within specification at 139ns and 1037ns. The 4.5V minimum input for converting 3.3V output will not meet the minimum off-time specification of 400ns. $t_{ON} = 868ns$, Frequency = 850kHz, $t_{OFF} = 315ns$.

Solution

Lower the switching frequency at lower input voltages to allow for higher duty cycles, and meet the 400ns minimum off-time at 4.5V input voltage. The off-time should be about 500ns, which includes a 100ns guard band. The duty cycle for (3.3V/4.5V) = ~73%. Frequency = $(1 - DC)/t_{OFF}$ or (1 - 0.73)/500ns = 540kHz. The switching frequency needs to be lowered to 540kHz at 4.5V input. $t_{ON} = DC/$ frequency, or 1.35 μ s. The f_{SFT} pin voltage is 1/3 of V_{IN}, and the I_{fSET} current equates to $38\mu A$ with the internal 39.2k. The I_{fSFT} current needs to be 24 μ A for 540kHz operation. As shown in Figure 19, a resistor can be placed from V_{OUT} to f_{SFT} to lower the effective l_{fSFT} current out of the f_{SFT} pin to $24\mu A$. The f_{SET} pin is 4.5V/3 = 1.5V and $V_{OUT} = 3.3V$, therefore 130k will source 14µA into the f_{SET} node and lower the I_{fSFT} current to 24µA. This enables the 540kHz operation and the 4.5V to 28V input operation for down converting to 3.3V output. The frequency will scale from 540kHz to 1.1 MHz over this input range. This provides for an effective output current of 8A over the input range.



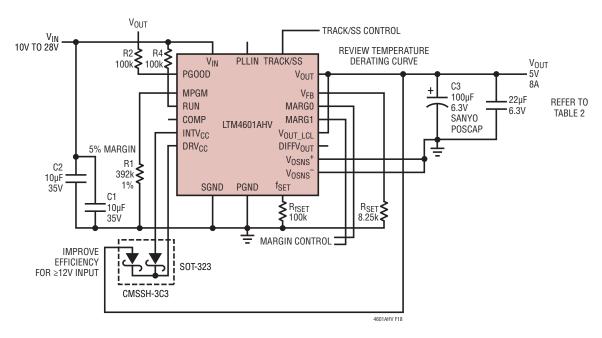


Figure 18. 5V at 8A Design Without Differential Amplifier

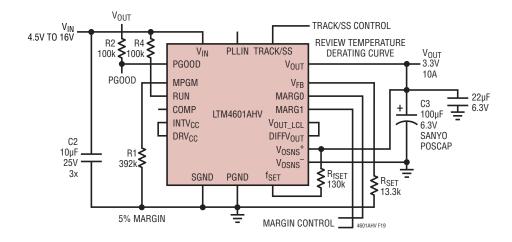


Figure 19. 3.3V at 10A Design



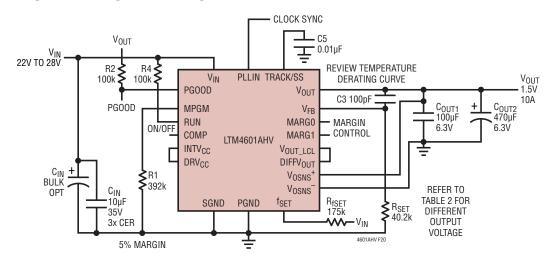


Figure 20. Typical 22V to 28V, 1.5V at 10A Design, 500kHz

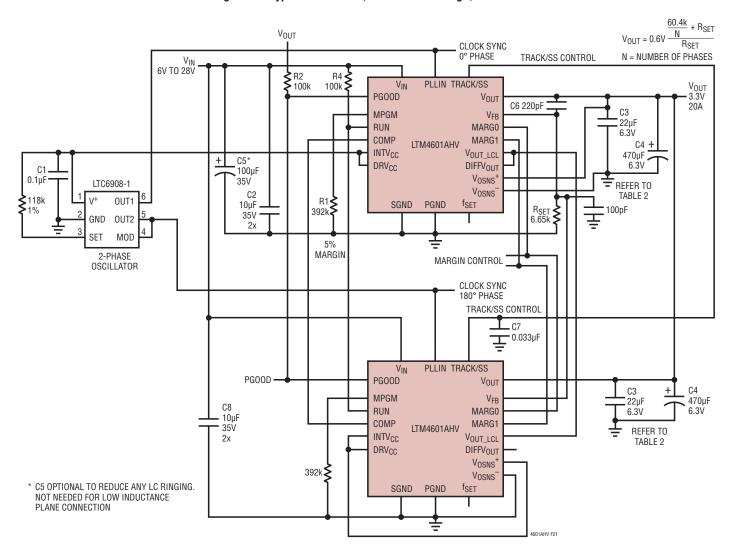


Figure 21. 2-Phase Parallel, 3.3V at 20A Design



TYPICAL APPLICATIONS

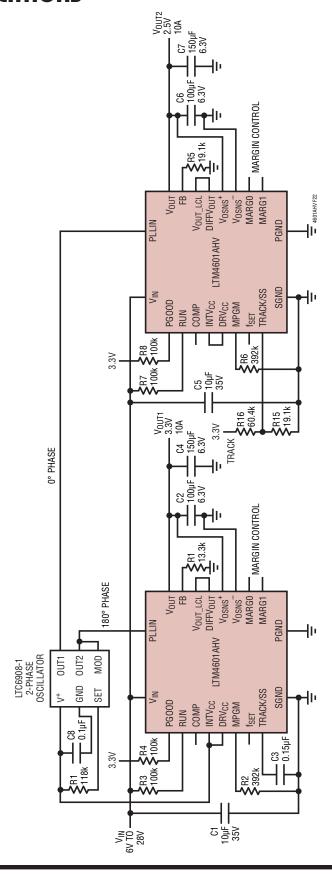


Figure 22. Dual Outputs (3.3V and 2.5V) with Coincident Tracking

TYPICAL APPLICATIONS

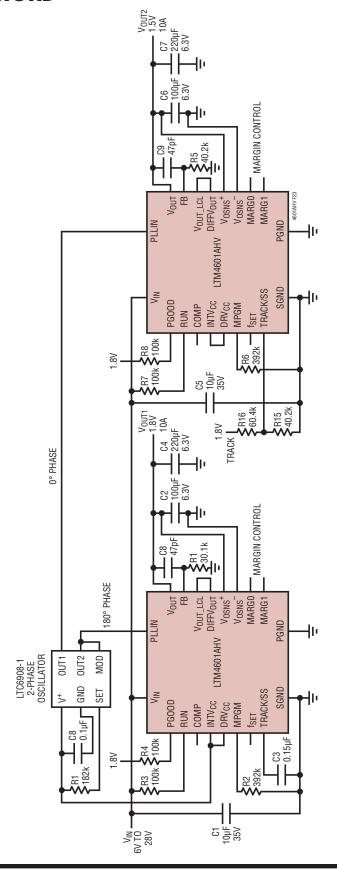
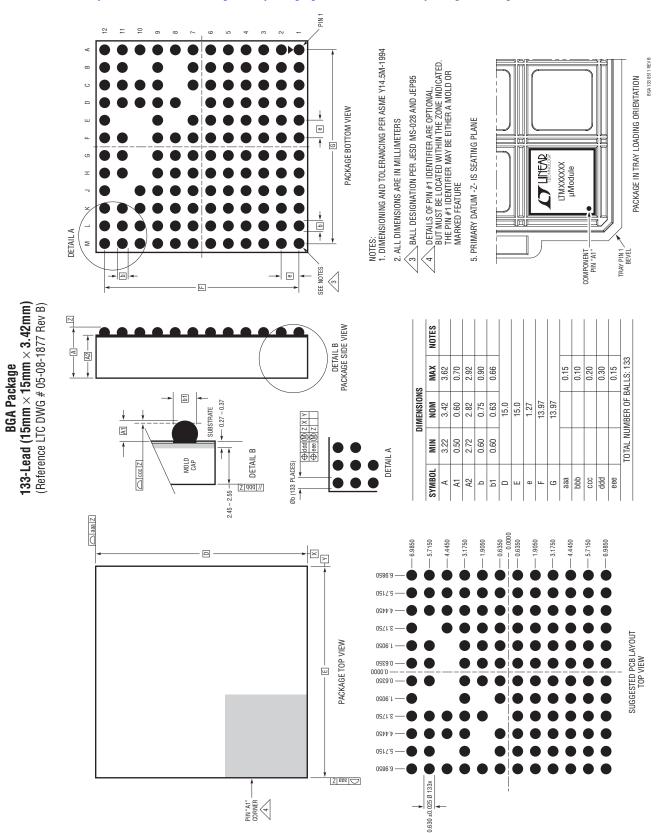


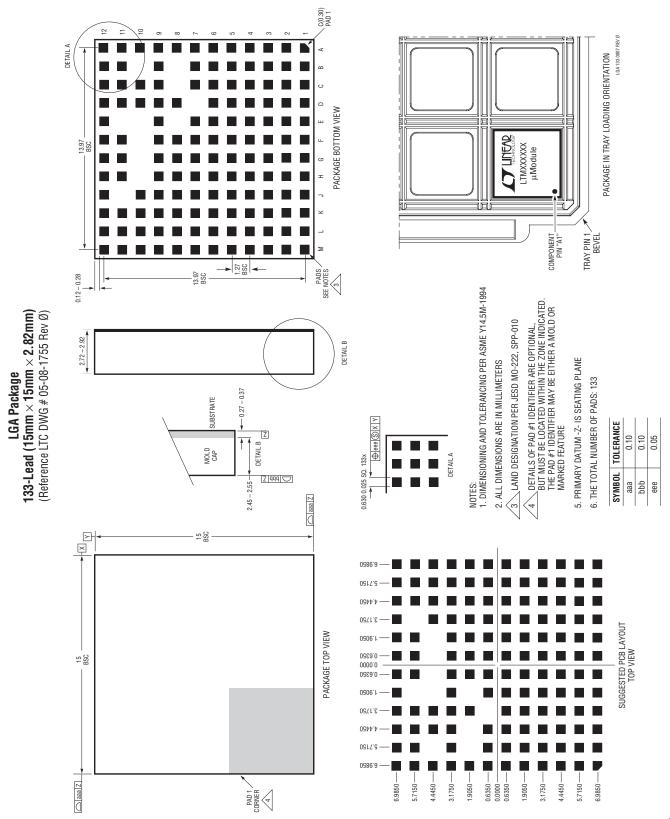
Figure 23. Dual Outputs (1.8V and 1.5V) with Coincident Tracking

LINEAR TECHNOLOGY

Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.



Please refer to http://www.linear.com/designtools/packaging/ for the most recent package drawings.



Pin Assignment Table 5 (Arranged by Pin Number)

Р	IN NAME	Р	IN NAME	P	IN NAME	PI	N NAME	P	IN NAME	P	IN NAME
A1	V _{IN}	B1	V _{IN}	C1	V _{IN}	D1	PGND	E1	PGND	F1	PGND
A2	V _{IN}	B2	V _{IN}	C2	V _{IN}	D2	PGND	E2	PGND	F2	PGND
A3	V _{IN}	В3	V _{IN}	C3	V _{IN}	D3	PGND	E3	PGND	F3	PGND
A4	V _{IN}	B4	V _{IN}	C4	V _{IN}	D4	PGND	E4	PGND	F4	PGND
A5	V _{IN}	B5	V _{IN}	C5	V _{IN}	D5	PGND	E5	PGND	F5	PGND
A6	V _{IN}	В6	V _{IN}	C6	V _{IN}	D6	PGND	E6	PGND	F6	PGND
A7	$INTV_{CC}$	В7	PGND	C7	PGND	D7	-	E7	PGND	F7	PGND
A8	PLLIN	B8	-	C8	-	D8	PGND	E8	-	F8	PGND
A9	TRACK/SS	В9	PGND	C9	PGND	D9	INTV _{CC}	E9	PGND	F9	PGND
A10	RUN	B10	-	C10	MTP1	D10	MPT2	E10	-	F10	-
A11	COMP	B11	MPGM	C11	f _{SET}	D11	MPT3	E11	-	F11	PG00D
A12	MPGM	B12	f _{SET}	C12	MARG0	D12	MARG1	E12	DRV _{CC}	F12	V_{FB}

PI	IN NAME	P	IN NAME	P	IN NAME	PI	N NAME	P	IN NAME	PI	N NAME
G1	PGND	H1	PGND	J1	V _{OUT}	K1	V _{OUT}	L1	V _{OUT}	M1	V _{OUT}
G2	PGND	H2	PGND	J2	V _{OUT}	K2	V _{OUT}	L2	V _{OUT}	M2	V _{OUT}
G3	PGND	Н3	PGND	J3	V_{OUT}	K3	V_{OUT}	L3	V_{OUT}	M3	V_{OUT}
G4	PGND	H4	PGND	J4	V_{OUT}	K4	V_{OUT}	L4	V_{OUT}	M4	V_{OUT}
G5	PGND	H5	PGND	J5	V_{OUT}	K5	V_{OUT}	L5	V_{OUT}	M5	V_{OUT}
G6	PGND	H6	PGND	J6	V_{OUT}	K6	V_{OUT}	L6	V_{OUT}	M6	V_{OUT}
G7	PGND	H7	PGND	J7	V_{OUT}	K7	V_{OUT}	L7	V_{OUT}	M7	V_{OUT}
G8	PGND	H8	PGND	J8	V_{OUT}	K8	V_{OUT}	L8	V_{OUT}	M8	V_{OUT}
G9	PGND	Н9	PGND	J9	V_{OUT}	K9	V_{OUT}	L9	V_{OUT}	M9	V_{OUT}
G10	-	H10	-	J10	V _{OUT}	K10	V _{OUT}	L10	V _{OUT}	M10	V _{OUT}
G11	SGND	H11	SGND	J11	-	K11	V _{OUT}	L11	V _{OUT}	M11	V _{OUT}
G12	PG00D	H12	SGND	J12	V_{OSNS}^+	K12	DIFFV _{OUT}	L12	V_{OUT_LCL}	M12	V _{OSNS} -

Pin Assignment Tables

PIN N	PIN NAME			
A1	VIN			
A2	VIN			
A3	VIN			
A4	VIN			
A5	VIN			
A6	VIN			
B1	VIN			
B2	VIN			
B3	VIN			
B4	VIN			
B5	VIN			
B6	VIN			
C1	VIN			
C2	VIN			
C3	VIN			
C4	VIN			
C5	VIN			
C6	VIN			

	PIN N	IAME
D1 D2 D3 D4 D5 D6 D8		PGND PGND PGND PGND PGND PGND PGND
E1 E2 E3 E4 E5 E6 E7		PGND PGND PGND PGND PGND PGND PGND
F1 F2 F3 F4 F5 F6 F7 F8 F9		PGND PGND PGND PGND PGND PGND PGND PGND
G1 G2 G3 G4 G5 G6 G7 G8 G9		PGND PGND PGND PGND PGND PGND PGND PGND
H1 H2 H3 H4 H5 H6 H7 H8		PGND PGND PGND PGND PGND PGND PGND PGND

Н9

PGND

ranged by	anged by Pin Function			
PIN	NAME			
J1 J2 J3 J4 J5 J6 J7 J8 J9 J10	VOUT VOUT VOUT VOUT VOUT VOUT VOUT VOUT			
K1 K2 K3 K4 K5 K6 K7 K8 K9 K10	VOUT VOUT VOUT VOUT VOUT VOUT VOUT VOUT			
L1 L2 L3 L4 L5 L6 L7 L8 L9 L10 L11	VOUT VOUT VOUT VOUT VOUT VOUT VOUT VOUT			
M1 M2 M3 M4 M5 M6 M7 M8 M9 M10	Vоит Vоит Vоит Vоит Vоит Vоит Vоит Vоит			

M10 M11

V_{OUT}

PIN NAME			
A7 A8 A9 A10 A11 A12	INTV _{CC} PLLIN TRACK/SS RUN COMP MPGM		
B12	f _{SET}		
C12	MARG0		
D12	MARG1		
E12	DRV _{CC}		
F12	V_{FB}		
G12	PG00D		
H12	SGND		
J12	V _{OSNS} ⁺		
K12	DIFFV _{OUT}		
L12	V _{OUT_LCL}		
M12	V _{OSNS} -		

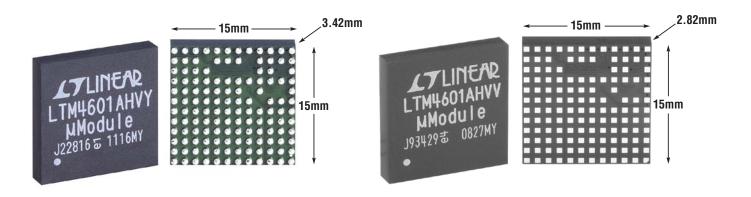
PIN NAME					
B7 B8	PGND -				
B9	PGND				
B10 B11	- MPGM				
C7 C8	PGND -				
C9	PGND				
C10 C11	MTP1				
	f _{SET}				
D7 D8 D9 D10 D11	PGND INTV _{CC} MTP2 MTP3				
E8 E9	- PGND				
E10 E11	-				
F10 F11	- PGOOD				
G10 G11	- SGND				
H10 H11	- SGND				
J11	-				

REVISION HISTORY

REV	DATE	DESCRIPTION	PAGE NUMBER
Α	12/10	Updated DIFFV _{OUT} Range specification in the Electrical Characteristics section.	3
		Updated MTP1, MTP2, MTP3 pin description in the Pin Functions section.	8
		Updated the Simplified Block Diagram.	8
		Edited various text in the Applications Information section.	10 to 21
		Updated Figures 7 and 8.	15
В	8/11	Added BGA package. Changes reflected throughout the data sheet.	1 to 30



PACKAGE PHOTOS



RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTC2900	Quad Supply Monitor with Adjustable Reset Timer	Monitors Four Supplies, Adjustable Reset Timer
LTC2923	Power Supply Tracking Controller	Tracks Both Up and Down, Power Supply Sequencing
LT3825/LT3837	Synchronous Isolated Flyback Controllers	No Opto-coupler Required, 3.3V, 12A Output, Simple Design
LTM4600	10A DC/DC μModule Regulator	Fast Transient Response, LTM4600HVMPV: -55°C to 125°C Tested
LTM4601	12A DC/DC µModule Regulator with PLL, Output Tracking/ Margining and Remote Sensing	Synchronizable, PolyPhase Operation to 48A, LTM4601-1 Version Has No Remote Sensing
LTM4602	6A DC/DC μModule Regulator	Pin Compatible with the LTM4600
LTM4603	6A DC/DC μModule Regulator with PLL and Output Tracking/Margining and Remote Sensing	Synchronizable, PolyPhase Operation, LTM4603-1 Version Has No Remote Sensing, Pin Compatible with the LTM4601
LTM4604A	4A Low Voltage DC/DC μModule Regulator	$2.375V \le V_{IN} \le 5.5V$, $0.8V \le V_{OUT} \le 5V$, $15\text{mm} \times 9\text{mm} \times 2.32\text{mm}$ (Ultrathin) LGA Package
LTM4608A	8A Low Voltage DC/DC μModule Regulator	$2.375V \le V_{IN} \le 5.5V$, $0.6V \le V_{OUT} \le 5V$; $15\text{mm} \times 9\text{mm} \times 2.82\text{mm}$ LGA Package
LTM8020	200mA, 36V _{IN} DC/DC μModule Regulator	$4V \le V_{IN} \le 36V$, $1.25V \le V_{OUT} \le 5V$, $6.25mm \times 6.25mm \times 2.32mm$ LGA Package
LTM8021	500mA, 36V _{IN} DC/DC μModule Regulator	$3V \le V_{IN} \le 36V$, $0.8V \le V_{OUT} \le 5V$, 11.25 mm $\times 6.25$ mm $\times 2.82$ mm LGA Package
LTM8022/ LTM8023	1A/2A, 36V _{IN} DC/DC μModule Regulator Family	$3.6V \le V_{IN} \le 36V$, $0.8V \le V_{OUT} \le 10V$, Pin Compatible, $11.25mm \times 9mm \times 2.82mm$ LGA Package