3-Phase Slim Power Controllers

SPR3 Series

INSTRUCTION MANUAL

DRW180136AE

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire.

 O2. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may
- ure to follow this instruction may result in explosion or fire.
- 03. Install on the device panel, and ground to the bolt for grounding separately. Failure to follow this instruction may result in fire or electric shock.

 O4. Do not connect, repair, or inspect the unit while connected to a power source.
- re to follow this instruction may result in fire or electric shock.
- 05. Check 'Connections' before wiring.
- ailure to follow this instruction may result in fire
- 06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage

01. Use the unit within the rated specifications.

- ilure to follow this instruction may result in fire or product damage
- 02. Use a dry cloth to clean the unit, and do not use water or organic solvent. ailure to follow this instruction may result in fire or electric shock
- 03. Keep the product away from metal chip, dust, and wire residue which flow allure to follow this instruction may result in fire or product damage
- 04. Since leakage current still flows right after turning off the power or in the
- output OFF status, do not touch the load terminal ure to follow this instruction may result in electric shock

Cautions during Use

- Follow instructions in 'Cautions during Use'.
- Otherwise, it may cause unexpected accidents.

 Use the product, after 3 sec of supplying power.

 Before use, set the mode and function according to the specification. Especially, be cautious that the product does not operate when OUT ADJ. is set to 0%. Since changing the mode / parameter during operation may result in malfunction, set the
- mode and function after disconnecting load output. • Re-supply the power to the unit after the unit is discharged completely. Failure to follow this instruction may result in malfunction.
- To ensure the reliability of the product, install the product on the panel or metal
- surface vertically to the ground.

 Install the unit in the well ventilated place.
- While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- · Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not wire to terminals which are not used.
- Since inter element can be damaged when using with coil load, inductive load, etc., the inrush current must be under the rated load current.
- Do not use near the equipment which generates strong magnetic force or high frequency noise.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude max. 2.000 m
- Pollution degrée 2 - Installation category III

Product Components

- Product ×1
- 11-pin connector ×1

Visit Autonics website to download manuals

Manual For the detailed information about communication, etc., please refer to the manuals, and be sure to follow cautions written in the technical descriptions.

• Insulating barrier ×4

Feedback control

F: Normal, feedback control (constant

current / constant voltage / constant

N: Normal control

F: Supports fuse

G Fuse

DAQMaster

- $\bullet \ \mathsf{DAQMaster} \ \mathsf{is} \ \mathsf{comprehensive} \ \mathsf{device} \ \mathsf{management} \ \mathsf{program}. \ \mathsf{It} \ \mathsf{is} \ \mathsf{available} \ \mathsf{for}$
- parameter setting, monitoring.

 Visit Autonics website to download the manual and the program.

Ordering Information

This is only for reference.

For selecting the specified model, follow the Autonics website.

SPR 3 - 0 0 0 0	
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- Rated load voltage
- 1: 110 VAC~ 2: 220 VAC~
- 3: 380 VAC~ 4: 440 VAC.~

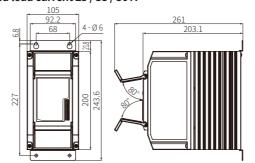
2 Rated load current Number: Rated load current (unit: A)

3 Option output

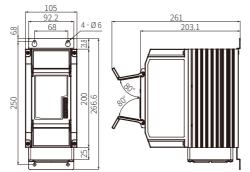
T: Alarm output + RS485 comm. output

Dimensions · Unit: mm, For the detailed drawings, follow the Autonics website.

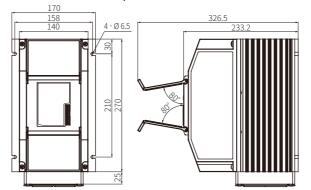
■ Rated load current 25 / 35 / 50 A



■ Rated load current 70 A



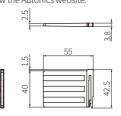
■ Rated load current 100 / 150 A

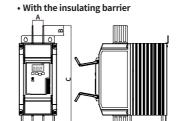


Insulating Barrier

It is recommended to use the included interphase barriers for insulation between phases and reduce influence from conductive materia

• Unit: mm, For the detailed drawings, follow the Autonics website.





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Rated load current	Α	В	С
25/35/50 A	30	28.2	300
70 A	30	28.2	300
100 / 150 A	40.5	50	370

Cautions during Installation

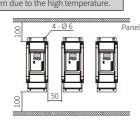
High Temperature Caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heatsink.
Failure to follow this instruction may result in a burn due to the high temperature.

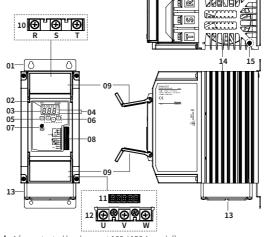
■ Mount space

· When installing multiple power controllers, keep space between power controllers for heat radiation

Horizontal: ≥ 50 mm, vertical: ≥ 100 mm



Unit Descriptions



01. Bracket [except rated load current 100 / 150 A model]

indicacoi						
	Function					
(green)	Turns on in the RUN mode.					
cator (green)	Turns on when adjusting load output in the manual control mode.					
)	Flashes in alarming status.					
d)	Turns on when load control outputs.					
	cator (green)					

03. Display part

RUN mode: Displays depending the front display setting Setting mode: Displays parameter and setting value

04. Unit indicator (V, A) Dependent on the disp

Display setting	٧	Α
Resistance and input	OFF	OFF
Voltage	ON	OFF
Current	OFF	ON
Power	ON	ON

05. [MODE] key

Enters parameter group, returns to RUN mode, moves parameters, and saves the

06. [◀], [▼], [▲] key

Enters SV setting mode and move digits.

07. Output limit adjuster (OUT ADJ)

08. Control input / comm. output terminal

(11-pin connector terminal) 09. Terminal protection cover 10. R, S, T load input terminal

11. Alarm output / power input terminal 12. U, V, W load output terminal

13. Cooling fan [Rated load current 70 / 100 / 150 A model] 14. Heatsink

Rated load current 100 / 150 A models have

left / right mounting holes.

15. Bolt for grounding (M4)

Specifications

Model	SPR3-1	SPR3-2	SPR3-3	SPR3-4		
Control phase	3-Phase	3-Phase				
Rated load voltage	110 VAC~ 50 / 60 Hz	220 VAC~ 50 / 60 Hz	380 VAC~ 50 / 60 Hz	440 VAC~ 50 / 60 Hz		
Rated load current	Rated load currer	nt 25 / 35 / 50 / 70	/ 100 / 150 A			
Display method	3 digit 7segment	LED				
Indicators		Operation / manual control indicator (green) Alarm / output / unit (V, A) indicator (red)				
Auto control input	DC 4 - 20 mA, 1 - 5 VDC==, ON / OFF contact (non-voltage input), pulse voltage (5 - 12 VDC==)					
Manual control input	External adjuster (10 kΩ), internal adjuster (output limit)					
Digital input (DI)	RUN / STOP selectable, AUTO / MAN selectable, RESET					
Alarm output	250 VAC∼ 3 A, 30 VDC= 3 A, 1c resistance load					
RS485 comm. output	Modbus RTU method					
Cooling method	Rated load current 25 / 35 / 50 A: natural cooling Rated load current 70 / 100 / 150 A: forced air cooling (with cooling fan)					
Unit weight (packaged)	Rated load current 25 / 35 / 50 A: \approx 4.1 kg (\approx 4.9 kg) Rated load current 70 A: \approx 4.2 kg (\approx 5 kg) Rated load current 100 / 150 A: \approx 8.7 kg (\approx 9.7 kg)					
Approval	(€					

Control method	Phase control	Cycle control	ON/OFF control	
constant voltage reedback/ constant power feedback		Fixed cycle	-	
Applied load	Resistance load, inductive load	Resistance load	Resistance load, inductive load	
Output range	0 to 98%	0 to 100%	0 / 100%	
Phase control output accuracy	Normal control: within ± 10% F.S. of rated load voltage Constant current feedback control: within ± 3% F.S. of rated load current Constant voltage feedback control: within ± 3% F.S. of rated load voltage Constant power feedback control: within ± 3% F.S. of rated load power			

Power supply	100 - 240 VAC∼ ±10% 50 / 60 Hz
Min. load current	1 A
Power consumption	Rated load current 25 / 35 / 50 A: \leq 14 VA Rated load current 70 A: \leq 22 VA Rated load current 100 / 150 A: \leq 32 VA
Insulation resistance	\geq 200 M Ω (500 VDC== megger)
Dielectric strength	2,000 VAC \sim 50 $/$ 60 Hz for 1 min (between input and power terminal)
Output leakage currents	≤ 10 mArms
Noise immunity	± 2 kV the square wave noise (pulse width: 1 μ s) by the noise simulator
Memory retention	≈ 10 years (when using non-volatile semiconductor memory type)
Vibration	0.75mm amplitude at frequency of 5 to 55Hz in each X, Y, Z direction for 2 hours
Vibration (malfunction)	0.5mm amplitude at frequency of 5 to 55Hz in each X, Y, Z direction for 10 min
Ambient temp.	-10 to 55 °C, storage: -20 to 80 °C (rated at no freezing or condensation)
Ambient humi.	35 to 85%RH, storage: 35 to 85%RH (rated at no freezing or condensation)

RS485 Communication Interface

Communication protocol	Modbus RTU
Connection	RS485
Application standard	Compliance with EIA RS485
Max. connections	31 units (address: 01 to 99)
Synchronous method	Asynchronous
Communication method	Two-wire half duplex
Communication distance	Max. 800 m
Communication speed	2400, 4800, 9600, 19200, 38400 bps
Communication response time	5 to 99 ms (default: 20 ms)
Start bit	1-bit (fixed)
Data bit	8-bit (fixed)
Parity bit	None, Even, Odd
Stop bit	1-bit. 2-bit

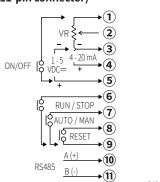
Load Output Formula

	Туре	Input		Formula	
		Current	DC 4 - 20 mA	Load output [%] = Control input [%] × output slope [%]	
-	Auto (AUTO)	Voltage	1-5 VDC==		
		RS485 communication		Load output [%] = RS485 [%]	
	Manual (MAN)		Internal adjuster		Load output [%] = internal adjuster [%]
			External adjuster	Load output [%] = external adjuster [%]	
			Load output [%] = internal adjuster [%] × External adjuster [%]		

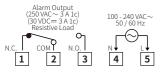
Connections

• Terminal configuration by model may differ depending on the supported spec.

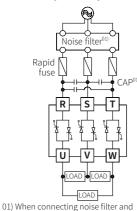
■ Control input / comm. output terminal (11-pin connector)



■ Alarm output / power input terminal



■ Load input / output terminal

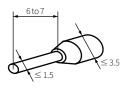


capacitor, it is appropriate for EMC. [CAP] Rated load voltage 110 / 220 VAC \sim : 1 μ F / 250 VAC \sim Rated load voltage 380 / 440 VAC~ : 0.47 µF / 500 VAC~

Cautions during Wiring

■ Control input / comm. output terminal (11-pin connector)

• Unit: mm, Use penhole terminals of size specified below.



■ Alarm output / power input & R, S, U load output terminal

• Unit: mm, Use crimp terminals of size specified below.



)	Rated load current Spe		Alarm output / power input	Load input / output
	25/35/50/	а	≥ 3.0	≥ 6.0
	70 A	b	≤ 6.0	≤ 16.0
	100 / 150 A	а	≥ 3.0	≥ 8.0
	100 / 150 A	b	≤ 6.0	≤ 26.0

• Cable / screw / tightening torque spec. is different depending on the load current. Be sure to the below before connection.

Rated load current	Spec.	Alarm output / power input	Load input / output
	Cable	AWG 18 to 14	AWG 13 to 4
25 / 35 / 50 / 70 A	Screw	M3	M6
23/33/30/101	Tightening torque	0.5 N m	5.5 to 6.0 N m
	Cable	AWG 18 to 14	AWG 4 to 2 / 0
100 / 150 A	Screw	M3	M8
100 / 100 / 1	Tightening torque	0.5 N m	6.5 to 7.0 N m

Alarm

- Supported alarms are different depending on the model.
- When several alarms occur at same time, the highest priority error is displayed based on priority.

Dui a uita .	itu Tuna Dianlau Op		Operation		Alayma valaasa	Model		
Priority	туре	Display	Alarm	Output	Alarm release	модеі		
1	SCR error	5Er	Error display flashes. Alarm indicator (ALM) flashes. Alarm output turns ON	display flashes. • Alarm indicators				Feedback control
2	Over current	display flashes.				Re-supply power.	Feedback control	
4	Heatsink over heat				- Alarm	stops.	RESET input Switch to stop	Normal / Feedback control
5	Over voltage	o-u		(SCR OFF)	(STOP) mode.	Feedback control		
3	Fuse break	F U S			Automatically cleared when	Normal / Feedback control		
6	Heater break	Н-Ь		Normal operation	returning within the setting range	Feedback control		
	1 2 4 5	2 Over current 4 Heatsink over heat 5 Over voltage 3 Fuse break 6 Heater	1 SCR error SEr 2 Over o-E 4 Heatsink over heat 5 Over voltage o-u 3 Fuse break 6 Heater H-b	Priority Type Display 1 SCR error 5 E r 2 Over current a - E 4 Heatsink over heat over heat voltage b E n indicator (ALM) flashes. 5 Over voltage a - u voltage 3 Fuse break F U 5 break 6 Heater H - b turns ON	Priority Type Display Alarm Output SCR error 5	Type Display Alarm Output		

SCR error alarm

Even though output is 0%, if the current of 10% or more of the rated load current flows for over 3 sec continuously, SCR error alarm occurs.

Over current alarm

This function protects the load from over current. If the current flows over the P2-7 over current alarm value and P2-8 over current alarm delay time, over current alarm occurs.

· Heatsink over heat alarm

When the temperature of a heatsink is over 85 $^{\circ}\text{C}$, heatsink over heat alarm occurs.

Over voltage alarm

This function protects the load from over voltage. If the current flows over the P2-9 over voltage alarm value and P2-10 over voltage alarm delay time, over voltage alarm occurs.

Fuse break alarm

When breaking fuse, not suppling load power, breaking load (single load), fuse brake alarm occurs. In the case of normal control model, real-time fuse break alarm is not available during output, and fuse break alarm operates at 0% output such as RESET.

 $Comparing the full load \ resistance \ value \ and \ the \ current \ load \ resistance \ value, if \ the \ current$ load resistivity is maintained under the P2-12 heater break alarm value for over 3 sec continuously, heater break alarm occurs. This alarm operates when control output is over 10% and load current is over 10% of the rated current. Output does not stop and operates

Current load resistance (%) = $\frac{\text{Full load resistance value}}{2} \times 100$ Current load resistance value

Mode Setting

	[MODE]	\rightarrow	Monitoring group	[MODE] 3 sec	\rightarrow	
	[MODE] 2 sec	\rightarrow	Parameter 1 group	[MODE] 3 sec	\rightarrow	
	[MODE] 4 sec	\rightarrow	Parameter 2 group	[MODE] 3 sec	\rightarrow	
RUN	[◄ + ▲ + ▼] 5 sec	\rightarrow	Parameter reset	[MODE]	\rightarrow	RUN
	6 - 9 terminal external contact	\rightarrow	RUN / STOP	Auto	\rightarrow	
	7 - 9 terminal external contact	\rightarrow	Auto / Manual control	Auto	\rightarrow	
	[▲ + ▼] 2 sec or 8 - 9 terminal	\rightarrow	Reset 01)	Auto	\rightarrow	

 $01) \ \ In the event of system anomalies and alarms, RESET input restarts the power controller. (parameters are not alarms) and alarms are not alarms are not alarms and alarms are not alarms. The power controller is also alarms are not alarms. The power controller is alarms are not alarms. The power controller is alarms are not alarms. The power controller is alarms are not al$

Parameter Setting

- \bullet Some parameters are activated / deactivated depending on the model or setting of
- other parameters. Refer to the description of each parameter.

 If any key is not entered for 30 sec in each parameter, it returns to RUN mode.
- [MODE] key: Saves current setting value and moves to the next parameter. ◄] key: Changes setting digits.
- $[\blacktriangle]$, $[\blacktriangledown]$ key: Changes setting values.

■ Monitoring group

Param	eter	Display	Display range		
M1-1	Monitoring value	In	0 to 100%		
M1-2	U-V line load voltage value	U - u	(Condition), and the last dell		
M1-3	M1-3 V-W line load voltage value		[Feedback control model] 0 to rated voltage range, V		
M1-4	W-U line load voltage value	ñ - N	o to fated voltage fallge, v		
M1-5	U-phase load current value	U-A	(Condition), control and dell		
M1-6	V-phase load current value	u - R	[Feedback control model] 0 to rated current range, A		
M1-7	W-phase load current value	¥-8	o to faced carrent range, //		
M1-8	Load power value	F - ñ	[Feedback control model] 0 to rated Power range, kW		
M1-9	Resistance value percentage	L-r	[Feedback control model] 0 to 100% • Displays the present resistance as percentage compared to the set resistance of full load auto recognition.		
M1-10	Heatsink temp.	ŁñP	0 to 100 °C		
M1-11	Power supply frequency	Fr9	50, 60 Hz		

■ Parameter 1 group

Parameter		Display	Default	Setting range
P1-1	SOFT START time	5-E	3	
P1-2	SOFT UP time	U-E	3	0 to 100 sec
P1-3	SOFT DOWN time	d-E	3	
P1-4	Output low-limit value	L-L	0	0 ≤ I-I ≤ H-I ≤ 100 %
P1-5	Output high-limit value	H-L	100	0 2 F-F 2 H-F 2 100 %
P1-6	Output slope ⁰¹⁾	SLP	100	0 to 100% • In case of auto control (AUTO), set the output slop limit proportional to control input for limit load power.

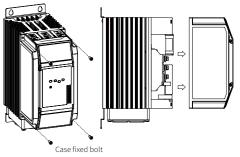
■ Parameter 2 group

Param	neter	Display	Default	Setting range				
P2-1	Control input ⁰¹⁾	int	420	420: DC 4 - 20 mA 1-5: 1 - 5 VDC == 512: 5 - 12 VDC == ONF: ON / OFF contact COM: RS485 communication				
P2-2	Control method	E-ñ	РЯ	*[Feedback control model] Set Control method PA Normal V-F* Phase Constant voltage feedback C-F* control W-F* Cycle control ONF ON/OFF control				
P2-3	Manual control (MAN) output limit method	ñĦn	1	I_R: Internal adjuster E_R: External adjuster E_I: Internal / external adjuster				
P2-4	Input correction 01)	inb	0.0					
P2-5	Input slope correction	5Pn	0.0	-99 to 99%				
P2-6	Front display	d1 5	In	*[Feedback control model] IN: Resistance and input U-V*: U-V line load voltage V-W*: V-W line load voltage W-U*: W-U line load voltage U-A*: U-phase load current V-A*: V-phase load current L-W*: Load power				
P2-7	Over current alarm value	ه 3 ه	120	[Feedback control model] 0 to 120%				
P2-8	Over current alarm delay time	ο£Ł	5	[Feedback control model] 0 to 100 sec				
P2-9	Over voltage alarm value	٥٥٥	120	[Feedback control model] 0 to 120%				
P2-10	Over voltage alarm delay time	out	5	[Feedback control model] 0 to 100 sec				
P2-11	Load resistance value auto recognition	F-L	oFF	[Feedback control model] OFF, ON It executes 100% control output for 3 sec and the load resistance value recognized automatically as the initial set when the function is ON.				
P2-12	Heater break alarm value	НЬи	10	[Feedback control model] 10 to 100%, OFF				
P2-13	Comm. address	Adr	0 1	[RS485 communication output model] 01 to 99				
P2-14	Comm. speed	ьP5	96	[RS485 communication output model] 24, 48, 96, 192, 384 bps (× 100)				
P2-15	Comm. parity bit	PrE	000	[RS485 communication output model] NON, EVE, ODD				
P2-16	Comm. stop bit	5 E P	2	[RS485 communication output model] 1, 2 bit				
P2-17	Comm. response time	r ï.E	20	[RS485 communication output model] 5 to 99 ms				
P2-18	Comm. write	۲ñ۳	E n.R	[RS485 communication output model] EN.A: Enable, DS.A: Disable				
P2-19	Lock	LoE	oFF	OFF LC1: Locks parameter 1 group LC2: Locks parameter 2 group				
P2-20	Parameter reset	ini	no	NO, YES				
01) Set	the below parameters avai	lable depen	ids on the o	ontrol input.				
Tv	no Control innut		Dienlay	Input Input slope Output Monitoring				

Туре	Control inp	Displ	ay	correction	Input slope correction	Output slope	Monitoring value	
Auto control (AUTO)	Current	DC 4 - 20 mA		420	0	0	0	The last control
	Voltage	1 - 5 VDC==	INT	1-5	0	0	0	
	Pulse voltage	5 - 12 VDC==		512	×	×	0	
(1010)	No-voltage	ON / OFF contact		ONF	×	×	0	
	RS485 communication			COM	×	×	×	input value 0 to 100%
Manual control (MAN)	Output	Internal adjuster	MAN	I_R	×	×	×	0 to 100%
		External adjuster		E_R				
	limit	Internal / external adjuster		E_I				

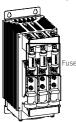
Replacement of Fuse

■ Case removal



■ Replacement of fuse

- Fuse none model is not equipped with a rapid fuse inside. Install the suitable fuse for rated load current of the model separately.
- The performance of the product is guaranteed only when using the fuse provided by us. For replacing the fuse, use the recommended fuse.





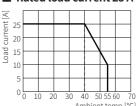
ated load urrent	Rec. fuse	Manufacturer	
5 A 50FE			
5 A	63ET	BUSSMANN	
0 A	80ET	DUSSIMAININ	
0 A	100FE		
00 A	660GH-160	HINODE	
50 A	660GH-200		

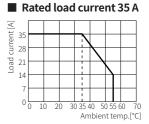
Bolt specification

Rated load current	Case fixed bolt	Fuse fixed bolt
25/35/50/70A	M3	M6
100 A	M4	Top: M8 Bottom: M6
150 A	M4	M8

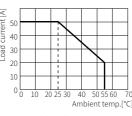
Derating Curve

■ Rated load current 25 A



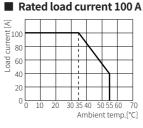


■ Rated load current 50 A



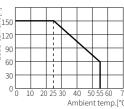


■ Rated load current 70 A



■ Rated load current 150 A

Ambient temp. [°C.



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