

# **Microprocessor Timers** RTx-410, 412, 414



CE

#### **Features**

Multi-function\*:

#### RTx-410:

A, B, C, D, As, Bs, Cs, Ds, Ar, Br, ABc, Pc

#### RTx-412:

Ac, Bc, A1c, B1c, C1c, D1c, Wd, Zsc

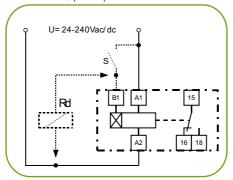
#### RTx-414

Ai, Ci, Asi, Csi, B1i, P1c, P2c, P3c, P4c, A2c

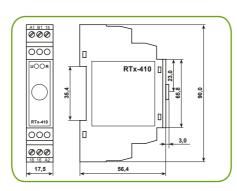
- Multi-range; choice of eight selectable time ranges from 0.01s to 100hr
- Analogue time setting
- Wide supply voltage range from 24 to 230V
- Binary control input B1
- LED power on indicator (Un)
- LED indicator of output state (R)
- · 35 mm DIN rail mounted

### Connection diagram

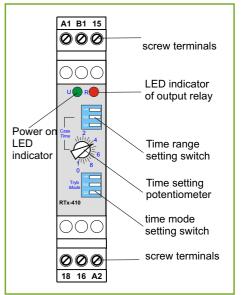
RTx-410, 412, 414



RTx-41x dimensions



#### Front panel view of RTx-41x



#### **Technical data**

Supply voltage options V<sub>x</sub> Supply voltage tolerance Frequency

24-240V AC/DC Time range

(0.8-1.1) Vx50 / 60Hz 0.01s - 100hr in eight sub-ranges (choosing by switch): (0.01-0.1s)\*\*; 0.1-1s; 1-10s; 10-100s; 1-10min; 10-100min; 1-10h; 10-100h

\*\* NOTE: Setting error may be higher than stated.

The time setting should be selected on try-out basis.

Restoration time

Contact ratings

- contact make

- contact break

- carry continuously

Repeatability

Setting error

Operating temperature

≤0.1s

5A

 $5A (220V, \cos \phi \le 0.4)$ 

0.1A (220V DC, L/R=40ms)

1% +10ms

±5% of the full scale ±10ms

(-25...+60)°C

### Information required with order

relay type **Example** RTx-410



# **Microprocessor Timers** RTx-420



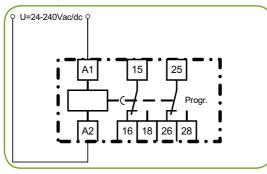
CE

#### **Features**

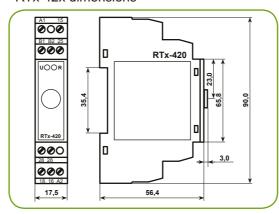
- Multi-function\*: A, B, C, D
- · Multi-range; choice of eight selectable time ranges from 0.01s to 100hr
- Analogue time setting
- Wide supply voltage range from 24 to 240V
- LED power on indicator (Un)
- LED indicator of output state (R)
- 35 mm DIN rail mounted
- 2 c/o outputs: deleyed+delayed/instantenous

#### **Connection diagram**

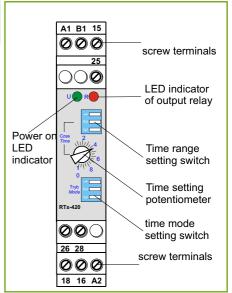
RTx-420



RTx-42x dimensions



Front panel view of RTx-420



#### **Technical data**

Supply voltage options V<sub>x</sub> 24-240V AC/DC Supply voltage tolerance (0.8-1.1) VxFrequency 50 / 60Hz Time range 0.01s - 100hr in eight sub-ranges

> (choosing by switch): (0.01-0.1s)\*\*; 0.1-1s; 1-10s; 10-100s; 1-10min; 10-100min; 1-10h; 10-100h

\*\* NOTE: Setting error may be higher than stated. The time setting should be selected on try-out basis.

Restoration time ≤ 0.1s

Contact ratings

- contact make - contact break

- carry continuously

Repeatability Setting error

Operating temperature

 $5A (220V, \cos_{\phi} \leq 0.4)$ 0.1À (220V DC, L/R=40ms)

5A

1% +10ms

±5% of the full scale ±10ms

(-25...+60)°C

Information required with order

relay type Example RTx-420



# **Microprocessor Timers** RTx-424



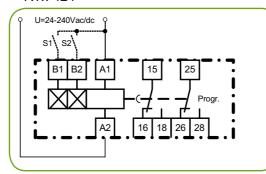
CE

#### **Features**

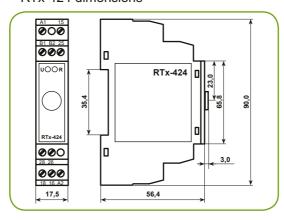
- Multi-function\*: A. B. C. D
- Multi-range; choice of eight selectable time ranges from 0.01s to 100hr
- · Analogue time setting
- Wide supply voltage range from 24 to 240V
- 2 Binary Logic Input B1 and B2
- LED power on indicator (Un)
- LED indicator of output state (R)
- 35 mm DIN rail mounted
- 2 c/o outputs: deleyed+delayed/instantenous

#### **Connection diagram**

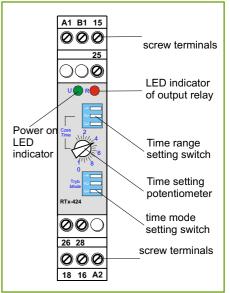
RTx-424



RTx-424 dimensions



Front panel view of RTx-424



#### **Technical data**

24-240V AC/DC Supply voltage options V<sub>x</sub> (0.8-1.1) VxSupply voltage tolerance Frequency 50 / 60Hz

0.01s - 100hr in eight sub-ranges Time range

> (choosing by switch): (0.01-0.1s)\*\*; 0.1-1s; 1-10s; 10-100s; 1-10min; 10-100min;

1-10h; 10-100h

\*\* NOTE: Setting error may be higher than stated. The time setting should be selected on try-out basis.

≤ 0.1s

Restoration time Contact ratings

- contact make

Operating temperature

- contact break  $5A (220V, \cos \phi \le 0.4)$ 0.1A (220V DC, L/R=40ms)

- carry continuously 5A

Repeatability 1% +10ms

Setting error ±5% of the full scale ±10ms

(-25...+60)°C

5A

## Information required with order

relay type Example RTx-424



# Microprocessor Star/delta Timer RTx-426



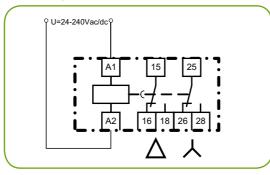
 $C \in$ 

#### **Features**

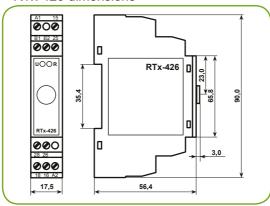
- · Star/delta starting timer for LV motors
- Multi-range; choice of eight selectable time ranges from 0.01s to 100hr
- Analogue time setting for star connection
- Time between star and delta arrangement: 50-350ms
- Wide range of power supply 24-240V AC/DC
- · 2 c/o outputs:
  - 26-26-28 star arrangement
  - 15-16-18 delta arrangement
- LED power on indicator (Un)
- LED indicator of delta arrangement (lit) and star arrangement (flushing) (R)
- 35 mm DIN rail mounted

#### **Connection diagram**

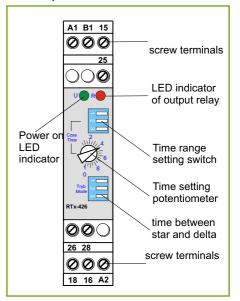
RTx-426



RTx-426 dimensions



Front panel view of RTx-426



#### **Technical data**

Supply voltage options V<sub>x</sub> 24-240V AC/DC Supply voltage tolerance (0.8-1.1) VxFrequency 50 / 60Hz

Time range for star arragement 0.01s - 100hr in eight sub-ranges (choosing by switch):

(0.01-0.1s)\*\*; 0.1-1s; 1-10s; 10-100s; 1-10min; 10-100min; 1-10h: 10-100h

The time setting should be selected on try-out basis.

Time range for delta arragement Restoration time

Contact ratings - contact make

- contact break

- carry continuously

Repeatability

Operating temperature

Setting error

50ms - 350ms step 50ms

≤ 0.1s

5A

 $5A (220V, \cos \phi \leq 0.4)$ 0.1A (220V DC, L/R=40ms)

5A

1% +10ms

±5% of the full scale ±10ms

(-25...+60)°C

### Information required with order

<sup>\*\*</sup> NOTE: Setting error may be higher than stated.

## **Modes of Operation Diagrams**

#### Key:

U - supply voltage UnR - output contacts state

T, T1, T2 - time setting

#### A function

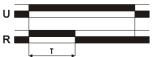
(time-delayed pick-up)



Timing commences upon application of the supply voltage. At the end of the timing the output contacts change their state and maintain this state until supply voltage is interrupted.

#### **B** function

(time-delayed drop-off)



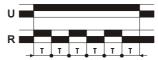
Inverse of A function. The output contacts change their state at the instant the supply voltage is applied. The output contacts change state to their rest position after the timing T is completed.

#### C function (cyclic operation)



Timing commences upon application of the supply voltage. At the end of time T the output relay is energised, timing T commences again and at the end of the timing range the output relay contacts change state to their rest position. The cycle repeats while the supply voltage is present.

#### **D** function (cyclic operation)



Inverse of C function. The output relay is energised and timing T commences at the instant the supply voltage is applied. At the end of time T the output relay contacts revert to their rest position and timing T commences again. At the end of T the output contacts are energised again and the cycle repeats.

## **E1 function** (single cycle operation)



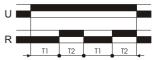
Timing T1 commences upon application of the supply voltage. At the end of time T1 the output contacts change their state and timing T2 commences. At the end of the timing range the output relays contacts change state to their rest position.

## **E2 function** (single cycle operation)



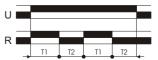
Inverse of E1 function. The output contacts change their state at the instant the supply voltage is applied until the timing T1 is completed. At the end of T1 the output contacts change state to their rest position and timing T2 commences. The output contacts change state at the end of time T2 and maintain this state while supply voltage is present.

#### E3 function (cyclic operation)



Timing T1 commences upon application of the supply voltage. At the end of time T1 the output relay is energised, timing T2 commences. At the end of the timing range T2 the output relays contacts change state to their rest position. The cycle repeats while supply voltage is present.

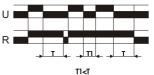
#### **E4 function** (cyclic operation)



Inverse of E3 function. The output contacts change their state at the instant the supply voltage is applied until timing T1 is completed. At the end of time T1 the output contacts change state to their rest position and time T2 commences. The cycle repeats while supply voltage is present.

#### **F** function

(time delay drop-off on supply voltage interruption)



The output contacts change their state upon application of the supply voltage. Timing commences upon the interruption of the supply voltage. At the end of the timing range the output relay contacts change state to their rest position.

## **Modes of Operation Diagrams**

- B1 and A1

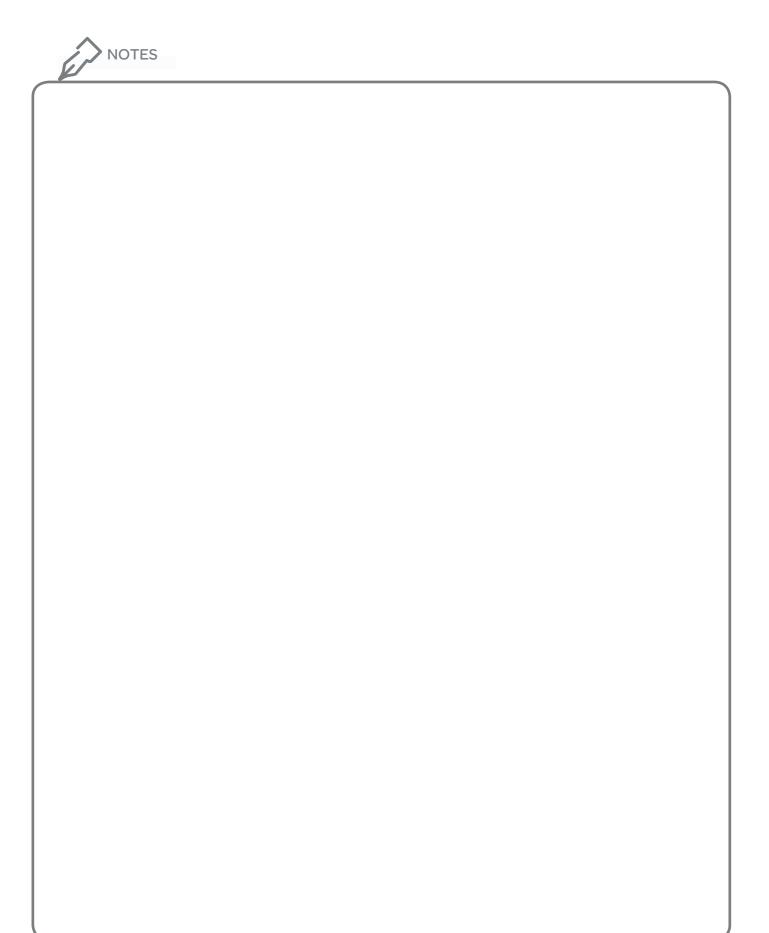
LED R

("R" on the front panel)

- lighting of red LED indicator

Key to read diagrams:

#### - supply voltage, - control contact (high state - short pulses of LED - the output relay is not energised; elapsing time is measured, until output - time setting, relay is energised, RTx-410 Time-delayed Cyclic operation Cyclic operation Time-delayed **B** drop-off (time-delayed pick-up (time-delayed drop-off) pick-up LED R LEDR Time-delayed pick-up **Bs** Time-delayed with Stop Cyclic operation Time-delayed drop-off Cyclic operation As Cs with Stop Ds with Stop s LEDR ||||| LEDR Time-delayed drop-off Abc and drop-off started by Pc started by Cosing Time-delayed drop-off Time-delayed pick-up Br with Reset closing control input s R R R R LEDR LED R LED R Time-delayed pick-up Time-delayed drop-off Time-delayed drop-off Time-delayed pick-up started by closing started by closing Вс A1c started by opening B1c started by opening control input control input control input control input S s R R LED R LED R LEDR Cyclic operation Cyclic operation Change of output Stoppage monitoring Zsc C1c started by opening D1c started by opening Wd relay state on enabling (Watch-Dog) control input control input control input T1 > T s s R ZATRZASK LED R LED R LEDR RTx-414 Impulse after time delay Cyclic im with Stop Impulse after time delay Cyclic impulse Cyclic impulse Asi with Stop S s IMPULS: 0,5s R R MPULS: 0,5s LEDR LEDR | | | | | | | | LED R Impulse after time delay Time measuring Time measuring Time measuring **B1i** started by opening P1c started by opening P2c started by change P3c started by closing control input control input of control input state control input s R R IMPULSY:0,5s LEDR LED R LED R LEDR Time measuring Time measuring started by change started by closing of control input state control input output relay NC output relay NC s R LEDR





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