Motor cable | PUR | chainflex® CFROBOT6

- For torsion applications
- PUR outer jacket
- Oil and coolant-resistant
- Flame retardant
- PVC and halogen-free
- Notch-resistant
- Hydrolysis and microbe-resistant

Dynamic information

Bend radius	e-chain® twisted	minimum 10 x d	
	flexible	minimum 8 x d	
	fixed	minimum 5 x d	
· Temperature	e-chain® twisted	-25 °C to +80 °C	

twisted

flexible -40 °C to +80 °C (following DIN EN 60811-504)

-50 °C to +80 °C (following DIN EN 50305) fixed 180 °/s

v max. twisted 60°/s2

Travel distance Robots and multi-axis movements. Class 1

Torsion ± 180°, with 1 m cable length, Class 3

Cable structure

Conductor Stranded conductor in especially bending-resistant design consisting of bare Core insulation

copper wires (following DIN EN 60228). Mechanically high-quality TPE mixture.

Core identification Black cores with white numerals 1-2, one core green-yellow.

> Low-adhesion, highly abrasion-resistant PUR mixture, adapted to suit the requirements in e-chains® (following DIN EN 50363-10-2).

Colour: Steel-blue (similar to RAL 5011)

Electrical information

Outer jacket

Nominal voltage 600/1000 V (following DIN VDE 0298-3)

4000 V (following DIN EN 50395) Testing voltage

Properties and approvals

Silicone-free

UV resistance High.

Oil-resistant (following DIN EN 50363-10-2), Class 3. Oil resistance

Flame retardant According to IEC 60332-1-2, CEI 20-35, FT1, VW-1

> Free from silicone which can affect paint adhesion (following PV 3.10.7 – status 1992).

Class 6.1.3.3

Following DIN EN 60754. Halogen-free

UL/CSA Style 10492 and 21223, 1000 V, 80 °C

NFPA NFPA Following NFPA 79-2012 chapter 12.9.

EHE EAC Certificate no. RU C-DE.ME77.B.02324 (TR ZU)

GP CTP Certificate no. C-DE.PB49.B.00420 (Fire safety)

CEI Following CEI 20-35.

Rouse Lead-free Following 2011/65/EU (RoHS-II).

Cleanroom According to ISO Class 1. Outer jacket material complies with

CF27.07.05.02.01.D, tested by IPA according to standard 14644-1.

(E_{CE} Following 2014/35/EU.

Guaranteed lifetime according to guarantee conditions (Page 22-23)

Torsion max. [°/m]	Torsion max. [°/m]	Torsion max. [°/m]
±150	±90	±30
±180	±120	±60
±150	±90	±30
	Torsion max. [°/m] ±150 ±180	Torsion max. [°/m] Torsion max. [°/m] ±150 ±90 ±180 ±120

- For extremely heavy duty applications with torsional movements
- Almost unlimited resistance to oil

Typical mechanical application areas

- Indoor and outdoor applications, UV resistant
- Especially for robots and multi-axis movements
- Robots, Handling, spindle drives

Part No.	Number of cores and conductor nominal cross section	Outer diameter (d) max.	Copper index	Weight
	[mm²]	[mm]	[kg/km]	[kg/km]
CFROBOT6.100.03	3G10.0	16.0	317	414
CFROBOT6.160.03	3G16.0	18.5	508	618
CFROBOT6.250.03	3G25.0	23.0	795	962
CEROBOT6 350 03 11)	3G35.0	25.5	1122	1208

¹¹⁾ Phase-out mode

Note: The given outer diameters are maximum values and may tend toward lower tolerance limits.

G = with green-yellow earth core x = without earth core

























igus chainflex CFR0B0T6