



RVT50AQFNWR00

LCD TFT Datasheet

Rev.1.2

2016-02-15

ITEM	CONTENTS	UNIT
LCD Type	TFT/Transmissive/Normally white	/
Size	5.0	Inch
Viewing Direction	12:00 (without image inversion)	O' Clock
Gray Scale Inversion Direction	6:00	O' Clock
LCM (W × H × D)	120.70 × 75.80 × 8.50	mm ³
Active Area (W × H)	108.00 × 64.80	mm ²
Dot Pitch (W × H)	0.045×0.135	mm ²
Number Of Dots	800 × (RGB) × 480	/
Driver IC	FT812	/
Backlight Type	12 LEDs	/
Surface Luminance	480	cd/m ²
Interface Type	SPI/QSPI	/
Color Depth	16.7M	/
Pixel Arrangement	RGB Vertical Stripe	/
Surface Treatment	Anti-glare	
Input Voltage	3.3	V
With/Without TSP	Resistive Touch Panel	/
Weight	85.47	g

Note 1: RoHS compliant

Note 2: LCM weight tolerance: ± 5%.

REVISION RECORD

REVNO.	REVDATE	CONTENTS	REMARKS
1.0	2015-10-06	Initial Release	
1.1	2015-11-30	Updating drawing about ZIF connector	
1.2	2016-02-15	Update LED Backlight Current and Input Voltage for LED Inverter, LCD Timing Characteristics information	

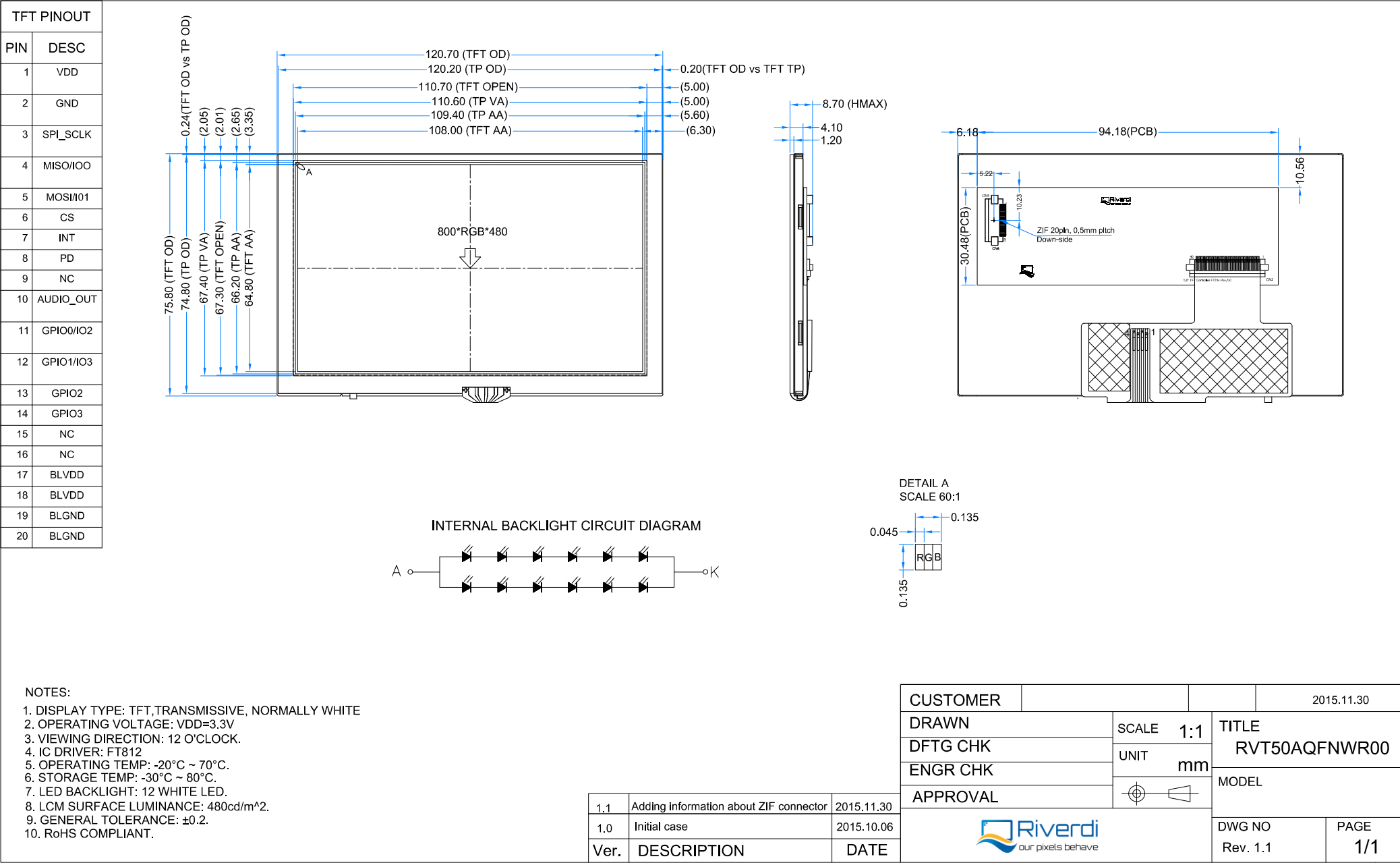
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1 MODULE CLASSIFICATION INFORMATION

RV	T	50	A	Q	F	N	W	R	00
1.	2.	3.	4.	5.	6.	7.	8.	9.	10.

1.	BRAND	RV – Riverdi
2.	PRODUCT TYPE	T – TFT Standard F – TFT Custom
3.	DISPLAY SIZE	35 – 3.5" 43 – 4.3" 50 – 5.0" 70 – 7.0"
4.	MODEL SERIAL NO.	A (A-Z)
5.	RESOLUTION	Q– 800x480 px
6.	INTERFACE	T – TFT LCD, RGB L – TFT LCD, LVDS S – TFT + Controller SSD1963 F – TFT + Controller FT812
7.	FRAME	N – No Frame F – Mounting Frame
8.	BACKLIGHT TYPE	W – LED White
9.	TOUCH PANEL	N – No Touch Panel R – Resistive Touch Panel C – Capacitive Touch Panel
10.	VERSION	00 (00-99)



3 ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	MIN	MAX	UNIT
Supply Voltage For Logic	VDD	-0.3	4.0	V
Input Voltage For Logic	VIN	VSS-0.5	VDD+0.3	V
LED forward current (each LED)	IF	-	60	mA
Operating Temperature	T _{OP}	-20	70	°C
Storage Temperature	T _{ST}	-30	80	°C
Humidity	RH	-	90% (Max 60°C)	RH

4 ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT	NOTES
Supply Voltage For Module	VDD	3.0	3.3	3.6	V	
Input Voltage for LED Inverter	BLVDD	2.8	3.3	5.5	V	
LED Backlight Current	IDD _{backlight}	-	290	363	mA	BLVDD=3.3V
LED Backlight Current	IDD _{backlight}	-	180	225	mA	BLVDD=5V
Input Leakage Current	I _{LKG}	-	-	-	μA	
Input Voltage 'H' level	V _{IH}	0.8VDD	-	VDD	V	
Input Voltage 'L' level	V _{IL}	-0.3	-	0.2VDD	V	

Note: The LED life time is defined as the module brightness decrease to 50% original brightness at Ta=25°C.

5 BACKLIGHT CHARACTERISTICS

ITEM	SYMBOL	MIN	TYP	MAX	UNIT
Voltage for LED backlight	V _I	17.4	18.3	19.6	V
Current for LED backlight	I _I	30	40	50	mA
LED Life Time	-	30000	50000	-	Hrs

Note: The LED Supply Voltage is defined by the numbers of LED at Ta=25°C and I_L= 40mA.

6 ELECTRO-OPTICAL CHARACTERISTICS

ITEM		SYMBOL	CONDITION	MIN	TYP	MAX	UNIT	REMARK	NOTE
Response Time		Tr+Tf	θ=0° ϕ=0° Ta=25	-	20	-	ms	Figure 1	4
Contrast Ratio		Cr		-	500	-	---	Figure 2	1
Luminance Uniformity		δ WHITE		75	80	-	%	Figure 2	3
Surface Luminance		Lv		440	480	-	cd/m²	Figure 2	2
Viewing Angle Range		θ	ϕ = 90°	40	50	-	deg	Figure 3	6
			ϕ = 270°	60	70	-	deg	Figure 3	
			ϕ = 0°	60	70	-	deg	Figure 3	
			ϕ = 180°	60	70	-	deg	Figure 3	
CIE (x, y) Chromaticity	Red	x	θ=0° ϕ=0° Ta=25	0.540	0.590	0.640	Figure 2	5	
		y		0.300	0.350	0.400			
	Green	x		0.298	0.348	0.398			
		y		0.520	0.570	0.620			
	Blue	x		0.095	0.145	0.195			
		y		0.060	0.110	0.160			
	White	x		0.270	0.320	0.370			
		y		0.310	0.360	0.410			

Note 1. Contrast Ratio(CR) is defined mathematically as below, for more information see Figure 1.

$$\text{Contrast Ratio} = \frac{\text{Average Surface Luminance with all white pixels (P1, P2, P3, P4, P5)}}{\text{Average Surface Luminance with all black pixels (P1, P2, P3, P4, P5)}}$$

Note 2. Surface luminance is the LCD surface from the surface with all pixels displaying white. For more information see Figure 2.

L_v = Average Surface Luminance with all white pixels (P1, P2, P3, P4, P5)

Note 3. The uniformity in surface luminance δ WHITE is determined by measuring luminance at each test position 1 through 5, and then dividing the maximum luminance of 5 points luminance by minimum luminance of 5 points luminance. For more information see Figure 2.

$$\delta \text{ WHITE} = \frac{\text{Minimum Surface Luminance with all white pixels (P1, P2, P3, P4, P5)}}{\text{Maximum Surface Luminance with all white pixels (P1, P2, P3, P4, P5)}}$$

Note 4. Response time is the time required for the display to transition from white to black (Rise Time, T_r) and from black to white (Decay Time, T_f). For additional information see FIG 1. The test equipment is Autronic-Melchers's ConoScope series.

Note 5. CIE (x, y) chromaticity, the x, y value is determined by measuring luminance at each test position 1 through 5, and then make average value.

Note 6. Viewing angle is the angle at which the contrast ratio is greater than 2. For TFT module the contrast ratio is greater than 10. The angles are determined for the horizontal or x axis and the vertical or y axis with respect to the z axis which is normal to the LCD surface. For more information see Figure 3.

Note 7. For viewing angle and response time testing, the testing data is based on Autronic-Melchers's ConoScope series. Instruments for Contrast Ratio, Surface Luminance, Luminance Uniformity, CIE the test data is based on TOPCON's BM-5 photo detector.

Note 8. For TFT module, Gray scale reverse occurs in the direction of panel viewing angle.

Figure 1. The definition of response time

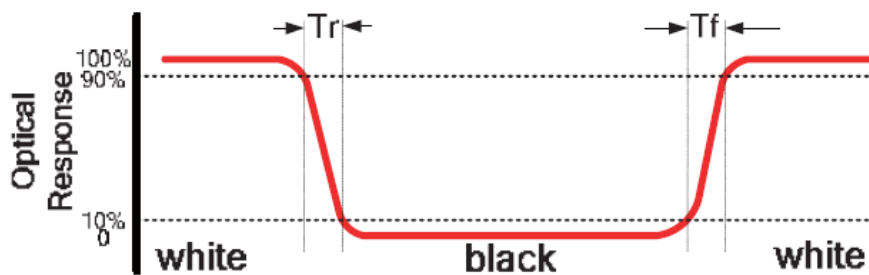


Figure 2. Measuring method for Contrast ratio, surface luminance, Luminance uniformity, CIE (x, y) chromaticity

A : 5 mm
 B : 5 mm
 H, V : Active Area
 Light spot size $\varnothing=5\text{mm}$, 500mm distance from the LCD surface to detector lens
 measurement instrument is TOPCON's luminance meter BM-5

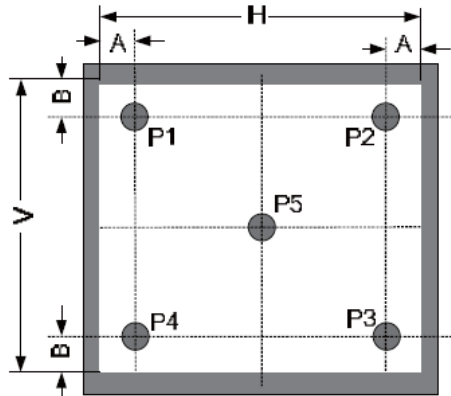
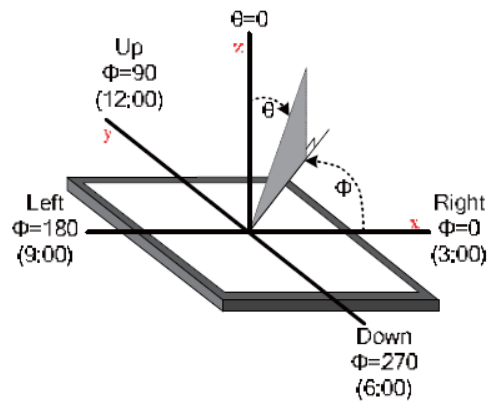


Figure 3. The definition of viewing angle



7 INTERFACE DESCRIPTION

PIN NO.	SYMBOL	DESCRIPTION
1	VDD	Power Supply
2	GND	Ground
3	SPI_SCLK	SPI SCK Signal, Internally 47k Pull UP
4	MISO/ IO0	SPI MISO Signal / IO0 Signal, Internally 47k Pull UP
5	MOSI/ IO1	SPI MOSI Signal / IO1 Slave Address Bit 0, Internally 47k Pull UP
6	CS	SPI Chip Select Signal , Internally 47k Pull UP
7	INT	Interrupt Signal, Active Low, Internally 47k Pull UP
8	PD	Power Down Signal, Active Low, Internally 47k Pull UP
9	NC	Not Connected
10	AUDIO_OUT	Audio Out Signal
11	GPIO0/IO2	SPI Single mode: General purpose IO0/ SPI Quad mode: SPI data line 2
12	GPIO1/IO3	SPI Single mode: General purpose IO1/ SPI Quad mode: SPI data line 3
13	GPIO2	General purpose IO2
14	GPIO3	General purpose IO3 or analog input for ADC
15	NC	Not Connected
16	NC	Not Connected
17	BLVDD	Backlight Power Supply, Can Be Connected to VDD
18	BLVDD	Backlight Power Supply, Can Be Connected to VDD
19	BLGND	Backlight Ground, Internally connected to GND
20	BLGND	Backlight Ground, Internally connected to GND

8 FT812 CONTROLLER SPECIFICATIONS

FT812 or EVE (Embedded Video Engine) simplifies the system architecture for advanced human machine interfaces (HMIs) by providing functionality for display, audio, and touch as well as an object oriented architecture approach that extends from display creation to the rendering of the graphics.

8.1 Serial host interface

Figure 4. SPI interface connection

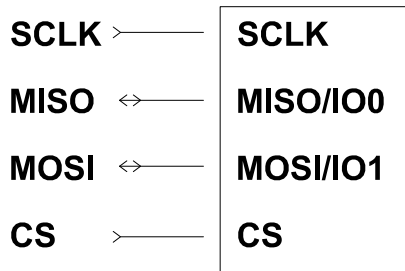
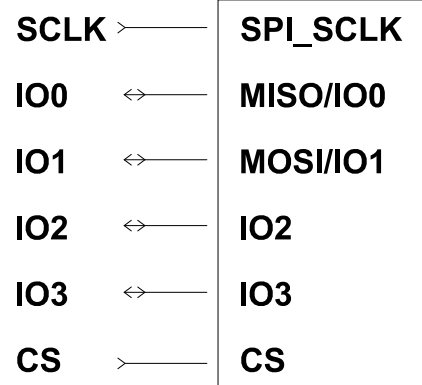


Figure 5. QSPI interface connection



SPI Interface – the SPI slave interface operates up to 30MHz.

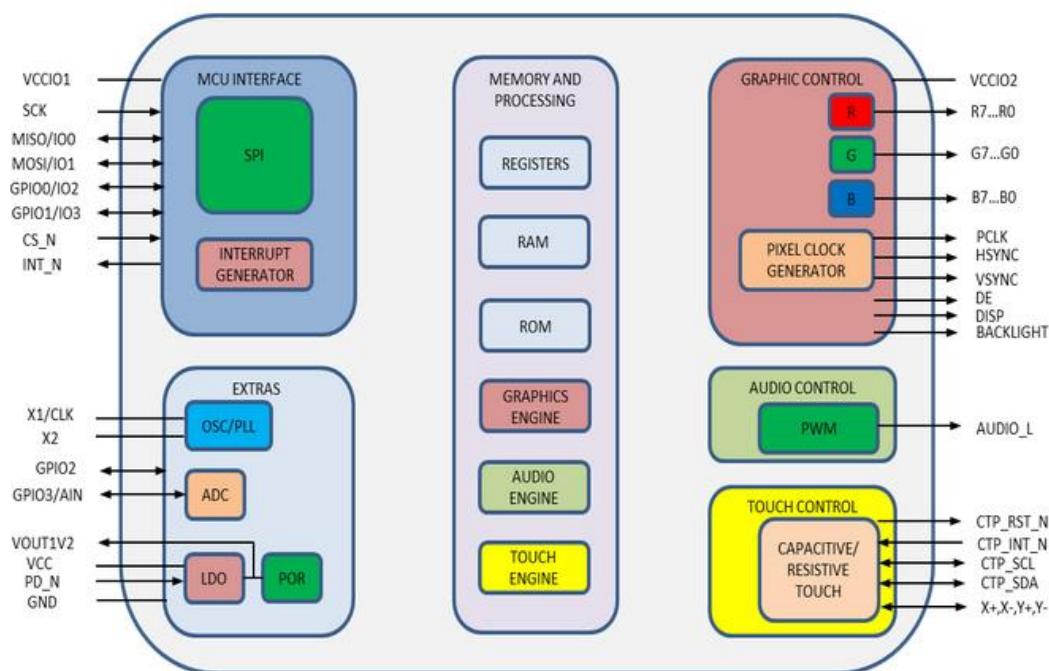
Only SPI mode 0 is supported. The SPI interface is selected by default (MODE pin is internally pulled low by 47k resistor).

QSPI Interface – the QSPI slave interface operates up to 30MHz. Only SPI mode 0 is supported. The QSPI can be configured as a SPI slave in SINGLE, DUAL or QUAD data bus modes.

By default the SPI slave operates in the SINGLE channel mode with MOSI as input from the master and MISO as output to the master. DUAL and QUAD channel modes can be configured through the SPI slave itself. To change the channel modes, write to register REG_SPI_WIDTH.

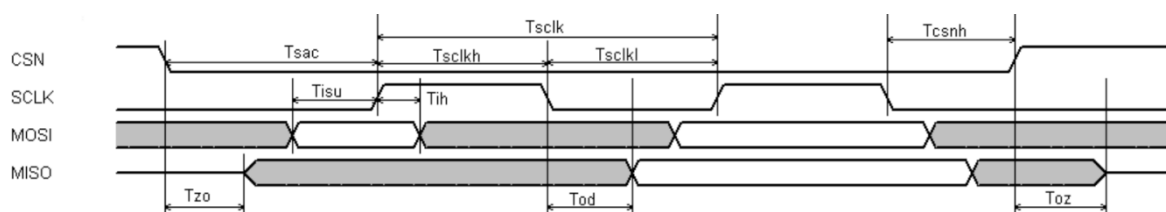
8.2 Block Diagram

Figure 6. FT812 Block diagram



8.3 Host interface SPI mode 0

Figure 7. SPI timing diagram



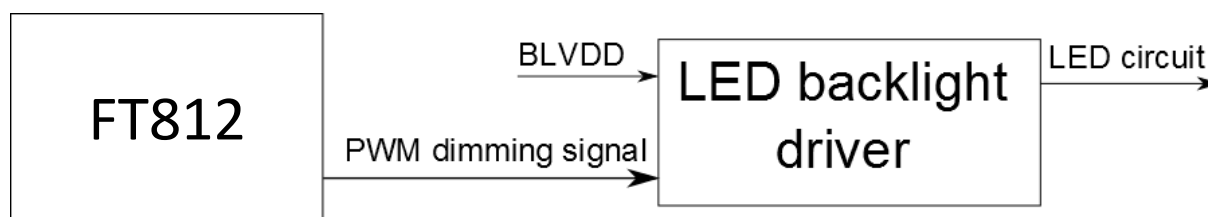
For more information about FT812 controller please go to official FT81x website.

<http://www.ftdichip.com/Products/ICs/FT81X.html>

8.4 Backlight driver block diagram

Backlight enable signal is internally connected to FT812 Backlight control pin. This pin is controlled by two FT812's registers. One of them specifies the PWM output frequency, second one specifies the duty cycle. Refer to FT812 datasheet for more information.

Figure 8. Backlight driver block diagram



9 LCD TIMING CHARACTERISTICS

9.1 Clock and data input time diagram

Figure 9. Horizontal input timing diagram

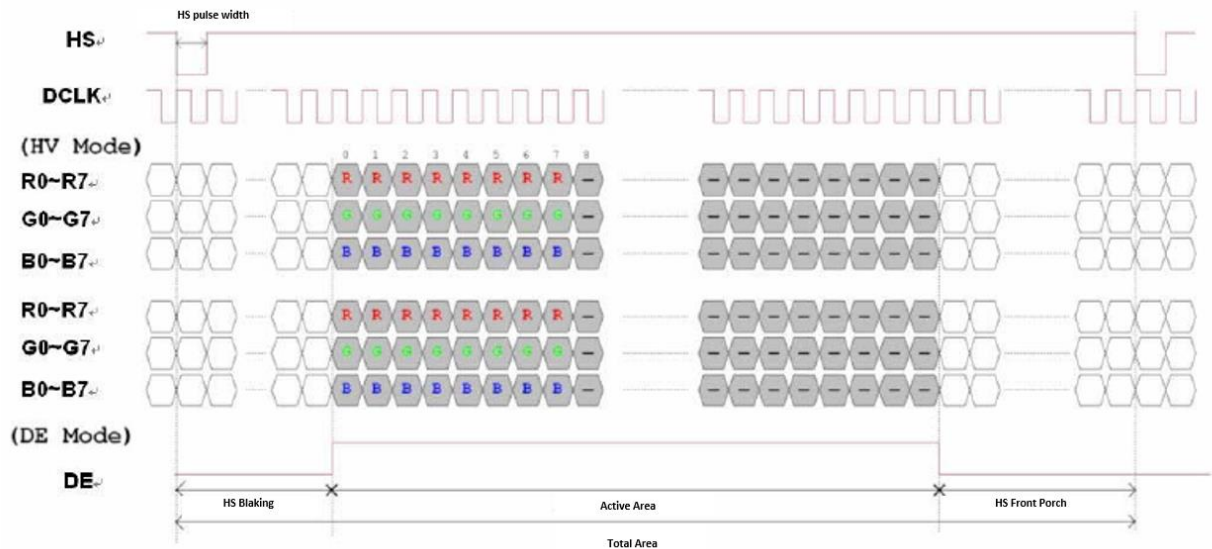
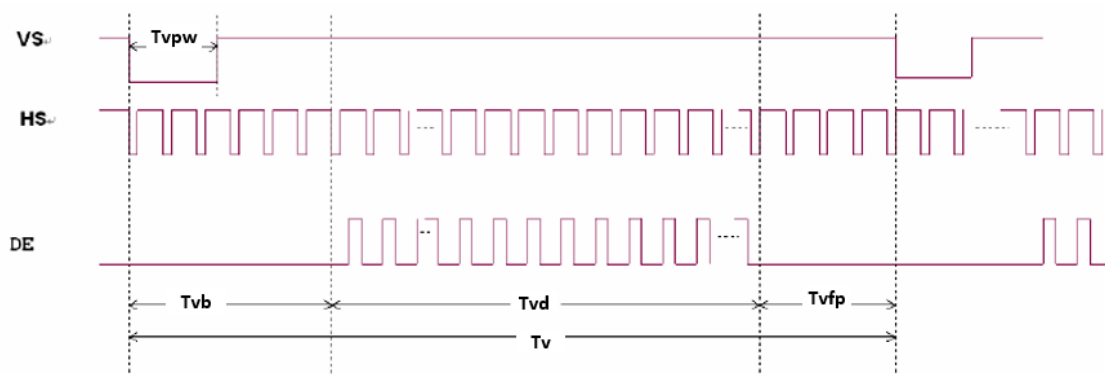


Figure 10. Vertical input timing diagram



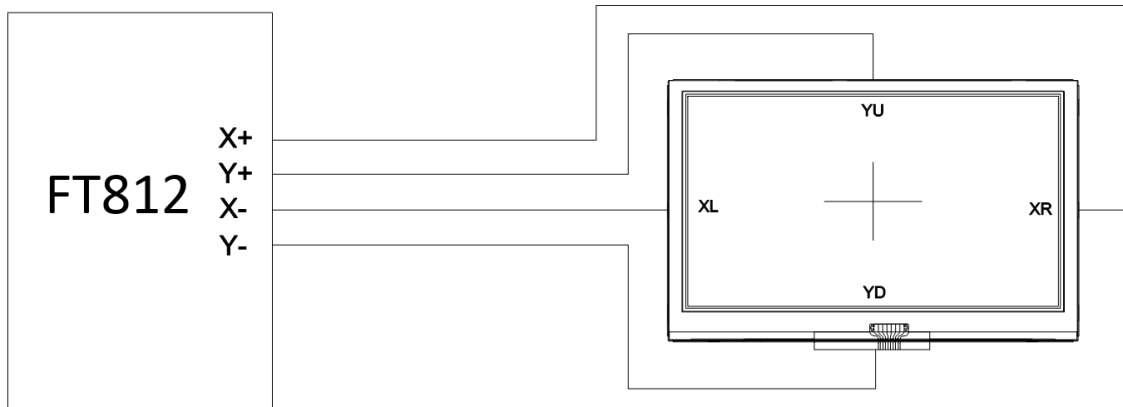
9.2 Parallel RGB timing table

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Horizontal Display Area	Thd	-	800	-	DCLK
DCLK Frequency	Fclk	-	30	50	MHz
One Horizontal Line	Th	889	928	1143	DCLK
HS pulse width	Thpw	1	48	255	DCLK
HS Blanking	Thb	-	88	-	DCLK
HS Front Porch	Thfp	1	40	255	DCLK
Vertical Display Area	Tvd	-	480	-	TH
VS period time	Tv	513	525	767	TH
VS pulse width	Tvpw	3	3	255	TH
VS Blanking	Tvb	-	32	-	TH
VS Front Porch	Tvfp	1	13	255	TH

10 TOUCH SCREEN PANEL SPECIFICATIONS

Resistive Touch Panel is directly connected to FT812 module. Therefore communication with Resistive touch panel is simplified to read registers of FT812.

Figure 11. Resistive Touch Panel Connection



10.1 Electrical characteristics

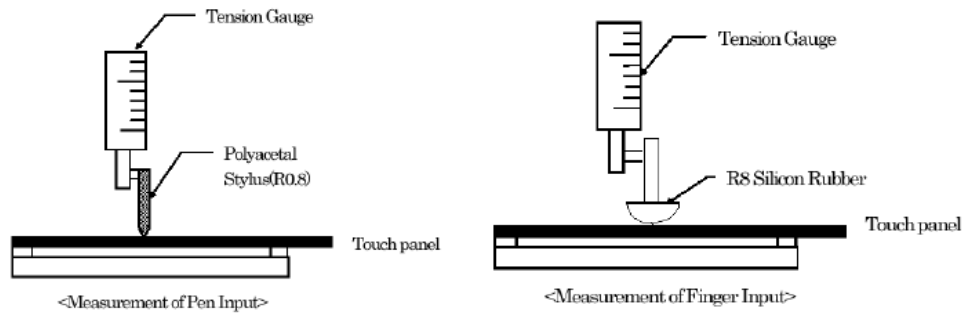
ITEM	VALUE			UNIT	REMARK
	Min.	Typ.	Max.		
Linearity	-1.5	-	1.5	%	Analog X and Y directions
Terminal Resistance	350	-	1000	Ω	X
	100	-	450	Ω	Y
Insulation Resistance	-	-	-	M Ω	DC 25V
Voltage	-	-	10	V	DC
Chattering	-	-	10	ms	100k Ω pull-up
Transparency	80	-	-	%	JIS K7105

Note: Avoid operating with hard or sharp material such as a ball point pen or a mechanical pencil except a polyacetal pen (tip R0.8mm or less) or a finger.

10.2 Mechanical characteristics

ITEM	VALUE			UNIT	REMARK
	Min.	Typ.	Max.		
Activation Force	80	-	-	gf	Note 1
Durability-Surface Scratching	Write 100,000	-	-	characters	Note 2
Durability-Surface Pitting	1,000,000	-	-	touches	Note 3
Surface Hardness	3	-	-	H	JIS K5400

Note 1: Force test condition, Input DC 5V on X direction, Drop off Polyacetal Stylus (R0.8), until output voltage stabilize, then get the R8.0mm Silicon rubber and do finger Activation force test. Next step, 9 points.



Note 2: Measurement surface area conditions, Scratch 100,000 times straight line on the film with a stylus change every 20,000 times with Force: 250gf, Speed: 60mm/sec by R0.8 polaceteal stylus.

Note 3: Pitting test, Pit 1, 000, 000 times on the film with R0.8 silicon rubber with Force: 250gf and Speed: 2 times/sec.

11 RELIABILITY TEST

NO.	TEST ITEM	TEST CONDITION
1	High Temperature Storage	80±2°C/240hours
2	Low Temperature Storage	-30±2°C/240hours
3	High Temperature Operating	70±2°C/240hours
4	Low Temperature Operating	-20±2°C/240hours
5	Temperature Cycle	-30±2°C~25~80±2°C × 20 cycles (30min.) (5min.) (30min.)
6	Damp Proof Test	60°C ±5°C × 90%RH/240hours
7	Vibration Test	Frequency 10Hz~55Hz Amplitude of vibration : 1.5mm Sweep: 10Hz~55Hz~10Hz, 12min X, Y, Z 2 hours for each direction.
8	Package Drop Test	Height:60 cm 1 corner, 3 edges, 6 surfaces
9	ESD Test	Air: ±4KV 150pF/330Ω 5 times Contact: ±2KV 150pF/330Ω 5 time

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