

## Three Phase AC Controller Modules

**PSUT 95**

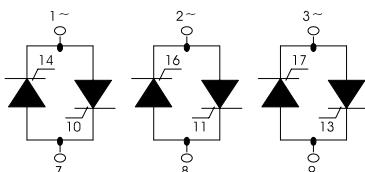
**I<sub>RMS</sub>**  
**V<sub>RRM</sub>**

**= 3 x 96A**  
**= 400-1600 V**

### Preliminary Data Sheet

V <sub>RSM</sub>	V <sub>RRM</sub>	Type
V <sub>DSM</sub>	V <sub>DRM</sub>	
500	400	PSUT 95/04
900	800	PSUT 95/08
1300	1200	PSUT 95/12
1500	1400	PSUT 95/14
*1700	*1600	PSUT 95/16

\* Delivery on request



Symbol	Test Conditions		Maximum Ratings	
I <sub>RMS</sub>	T <sub>C</sub> = 85 °C, 50-400 Hz (per phase)		96	A
I <sub>TRMS</sub>	T <sub>VJ</sub> = T <sub>VJM</sub>		69	A
I <sub>TAVM</sub>	T <sub>C</sub> = 85 °C	180° sine	44	A
I <sub>TSM</sub>	T <sub>VJ</sub> = 45°C	t = 10 ms (50 Hz), sine	1150	A
	V <sub>R</sub> = 0	t = 8.3 ms (60 Hz), sine	1230	A
	T <sub>VJ</sub> = T <sub>VJM</sub>	t = 10 ms (50 Hz), sine	1000	A
	V <sub>R</sub> = 0	t = 8.3 ms (60 Hz), sine	1100	A
∫ i <sup>2</sup> dt	T <sub>VJ</sub> = 45°C	t = 10 ms (50 Hz), sine	6600	A <sup>2</sup> s
	V <sub>R</sub> = 0	t = 8.3 ms (60 Hz), sine	6280	A <sup>2</sup> s
	T <sub>VJ</sub> = T <sub>VJM</sub>	t = 10 ms (50 Hz), sine	5000	A <sup>2</sup> s
	V <sub>R</sub> = 0	t = 8.3 ms (60 Hz), sine	5080	A <sup>2</sup> s
(di/dt) <sub>cr</sub>	T <sub>VJ</sub> = T <sub>VJM</sub>	repetitive, I <sub>T</sub> = 150 A	100	A/μs
	f = 50Hz, t <sub>P</sub> = 200μs			
	V <sub>D</sub> = 2/3 V <sub>DRM</sub>			
	I <sub>G</sub> = 0.3 A	non repetitive, I <sub>T</sub> = I <sub>TAVM</sub>	500	A/μs
	di <sub>G</sub> /dt = 0.3 A/μs			
(dv/dt) <sub>cr</sub>	T <sub>VJ</sub> = T <sub>VJM</sub>	V <sub>DR</sub> = 2/3 V <sub>DRM</sub>	1000	V/μs
	R <sub>GK</sub> = ∞, method 1 (linear voltage rise)			
P <sub>GM</sub>	T <sub>VJ</sub> = T <sub>VJM</sub>	t <sub>P</sub> = 30μs	10	W
	I <sub>T</sub> = I <sub>TAVM</sub>	t <sub>P</sub> = 300μs	5	W
P <sub>GAVM</sub>			0.5	W
V <sub>RGM</sub>			10	V
T <sub>VJ</sub>			-40 ... + 125	°C
T <sub>VJM</sub>			125	°C
T <sub>stg</sub>			-40 ... + 125	°C
V <sub>ISOL</sub>	50/60 HZ, RMS	t = 1 min	2500	V ~
	I <sub>ISOL</sub> ≤ 1 mA	t = 1 s	3000	V ~
M <sub>d</sub>	Mounting torque	(M5)	5	Nm
	Terminal connection torque	(M3)	1.5	Nm
		(M5)	5	Nm
Weight	typ.		220	g

### Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glasspassivated chips
- Package with metal base plate
- UL registered E 148688

### Applications

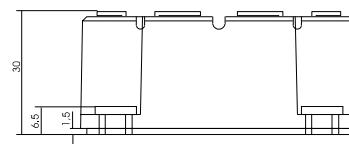
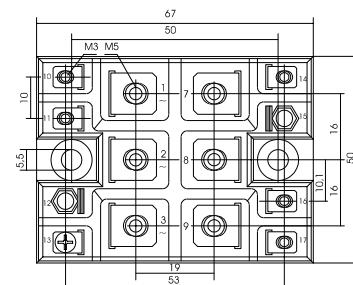
- Switching and control of three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling capability
- High power density

### Package, stil and outline

Dimensions in mm (1mm = 0.0394")



<b>Symbol</b>	<b>Test Conditions</b>		<b>Characteristic Value</b>		
$I_D, I_R$	$T_{VJ} = T_{VJM}$ , $V_R = V_{RRM}$ , $V_D = V_{DRM}$		$\leq$	5	mA
$V_T$	$I_T = 150A$ , $T_{VJ} = 25^\circ C$		$\leq$	1.57	V
$V_{TO}$	For power-loss calculations only ( $T_{VJ} = T_{VJM}$ )			0.85	V
$r_T$				4.8	$m\Omega$
$V_{GT}$	$V_D = 6V$	$T_{VJ} = 25^\circ C$	$\leq$	1.0	V
		$T_{VJ} = -40^\circ C$	$\leq$	1.6	V
$I_{GT}$	$V_D = 6V$	$T_{VJ} = 25^\circ C$	$\leq$	100	mA
		$T_{VJ} = -40^\circ C$	$\leq$	150	mA
$V_{GD}$	$T_{VJ} = T_{VJM}$	$V_D = 2/3 V_{DRM}$	$\leq$	0.2	V
$I_{GD}$	$T_{VJ} = T_{VJM}$	$V_D = 2/3 V_{DRM}$	$\leq$	5	mA
$I_L$	$T_{VJ} = 25^\circ C$ , $t_P = 10\mu s$ $I_G = 0.3A$ , $di_G/dt = 0.3A/\mu s$		$\leq$	200	mA
$I_H$	$T_{VJ} = 25^\circ C$ , $V_D = 6V$ , $R_{GK} = \infty$		$\leq$	150	mA
$t_{gd}$	$T_{VJ} = 25^\circ C$ , $V_D = 1/2 V_{DRM}$ $I_G = 0.3A$ , $di_G/dt = 0.3A/\mu s$		$\leq$	2	$\mu s$
$t_q$	$T_{VJ} = T_{VJM}$ , $I_T = 20A$ , $t_P = 200\mu s$ , $V_R = 100V$ $-di/dt = 10A/\mu s$ , $dv/dt = 15V/\mu s$ , $V_D = 2/3 V_{DRM}$			150	$\mu s$
$R_{thJC}$	per thyristor; sine $180^\circ el$			0.66	K/W
	per module			0.11	K/W
$R_{thJK}$	per thyristor; sine $180^\circ el$			0.93	K/W
	per module			0.155	K/W
$d_s$	Creeping distance on surface			8.0	mm
$d_A$	Creeping distance in air			4.5	mm
$a$	Max. allowable acceleration			50	$m/s^2$