# Remote I/O Boxes (EtherCAT)



## **ADIO-EC (IO-Link Master Type)**

## PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

#### **Features**

- The upper level communication protocol: EtherCAT
- The lower level communication protocol: IO-Link Ver. 1.1 (port class: Class A)
- · Housing material: Zinc Die casting
- Protection rating: IP67, IP69K
- $\bullet$  The daisy chain allows the power supply using the connection technology in a standardized 7/8" connector
- The maximum output current of power supply: 2 A per port
- I/O port settings and status monitoring (cable short / disconnection, connection status, etc.)
- · Supports digital input filter

#### **Safety Considerations**

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ▲ symbol indicates caution due to special circumstances in which hazards may occur.

**⚠ Warning** Failure to follow instructions may result in serious injury or death.

01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention

Failure to follow this instruction may result in personal injury, economic loss or

02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

03. Do not connect, repair, or inspect the unit while connected to a power source.

Failure to follow this instruction may result in fire.

04. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

**05.** Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

06. Do not touch the product during operation or for a certain period of time **after stopping.**Failure to follow this instruction may result in burn.

↑ Caution Failure to follow instructions may result in injury or product damage.

 ${\bf 01.}\ Use\ the\ unit\ within\ the\ rated\ specifications.$ 

Failure to follow this instruction may result in fire or shortening the life cycle of the

02. Use a dry cloth to clean the unit, and do not use water or organic solvent.

Failure to follow this instruction may result in fire.

03. Keep the product away from metal chip, dust, and wire residue which flow

Failure to follow this instruction may result in fire or product damage.

O4. Connect the cable correctly and prevent poor contact.

Failure to follow this instruction may result in fire or product damage.

O5. Do not connect or cut off the wire of the cable while operating the unit. Failure to follow this instruction may result in fire or product damage

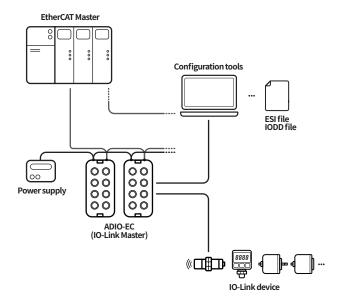
## **Cautions during Use**

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected
- The UA power (actuator power) and US power (sensor power) should be insulated by the individually isolated power device
- Power supply should be insulated and limited voltage/current or Class 2, SELV power supply device
- Use the rated standard cables and connectors. Do not apply excessive power when
- connecting or disconnecting the connectors of the product.

  Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.
  For stable operation, use shield wire and ferrite core, when wiring communication wire, power wire, or signal wire.
- Do not use near the equipment which generates strong magnetic force or high frequency noise.
- Do not connect, or remove this unit while connected to a power source
- This unit may be used in the following environments
- Indoors (in the environment condition rated in 'Specifications')
- Altitude max. 2,000 m
- Pollution degree 2
- Installation category II

#### Configuration of ADIO-EC-ILM

The figure below shows the EtherCAT network and the devices that compose it. For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals. Download the manuals from the Autonics website.



STEP		Reference manual	
	Install and ground the ADIO		
	1		
Hardware installation	Connect the ports of ADIO	Product Manual for ADIO-FC-II M	
mstattation	1	IOI ADIO EC ILM	
	Supply power to the ADIO		
IO-Link device settings	Set parameters and functions of IO-Link device	atIOLink User Manual	
	+		
EtherCAT Master	Integrate the ADIO-EC-ILM to the TwinCAT 3		
↓ ADIO-EC-ILM	1	TwinCAT 3 Guide 01)	
ADIO-EC-ILM	Set the ports of ADIO-EC-ILM		
Checking the operation Check the indicators		Product Manual for ADIO-EC-ILM	

<sup>01)</sup> The purpose of this document is to provide supplementary information for users' convenience.

The project planning software of the upper level communication system may be different depending on the user's environment. For more information, refer to the manufacturer's manual.

#### ■ The supported objects

Operation mode	Safe State <sup>01)</sup>	Vali- dation	Data Storage	Input Filter <sup>01)</sup>	Vendor ID	Device ID	Cycle Time
Digital Input	-	-	-	0	-	-	-
Digital Output	0	-	-	-	-	-	-
IO-Link Input	-	0	0	-	0	0	0
IO-Link Output	-	0	0	-	0	0	0
IO-Link Input/Output	-	0	0	-	0	0	0

<sup>01)</sup> Unsupported on the atIOLink

## Software

Download the installation file and the manuals from the Autonics website.

#### ■ atIOLink

"atlOLink" is the Port and Device Configuration Tool (PDCT). It supports the settings for ports and devices in the Field Network.

## **Ordering Information**

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

ADIO - 0 - 2 3 4 5 6 7 3 - 9

Communication

EC: EtherCAT

2 Material

M: Zinc die casting

**3 Port class**A: Class A

Ports

No mark: M12

08: 8-port **⑤** I/O connector type

**3** I/O configuration

A: Digital input 16-CH, digital output 8-CH

**7** Power connector type

No makr: 7/8", 5-pin

**3** I/O specification

N: NPN P: PNP

**1**O-Link product type

ILM: IO-Link Master

## **Product Components**

- Product  $\times$  1
- Name plates  $\times$  20
- M4×10 screw with washer × 1
- Instruction manual  $\times$  1
- Waterproof cover  $\times$  4

## **Sold Separately**

- Name plates
- Waterproof cover
- $\bullet$  Communication cable for the PDCT port: SCM-USM12

## **Connections**

#### ■ Ethernet port

M12 (Socket-Female), D-coded	Pin	Function	Description
4 1	1	TX+	Transmit Data +
(0 0)	2	RX+	Receive Data +
\o o f	3	TX -	Transmit Data -
3 1 2	4	RX -	Receive Data -

## ■ Power supply port

OUT (7/8", Socket- Female)	IN (7/8", Plug-Male)	Pin	Function	Description
4 5	5 4	1, 2	0 V	Sensor and actuator supply
3(0)	3	3	F.G.	Frame ground
2 0 1		4	+24 VDC==	Sensor supply
	1 — 2	5	+24 VDC==	Actuator supply

#### ■ PDCT port

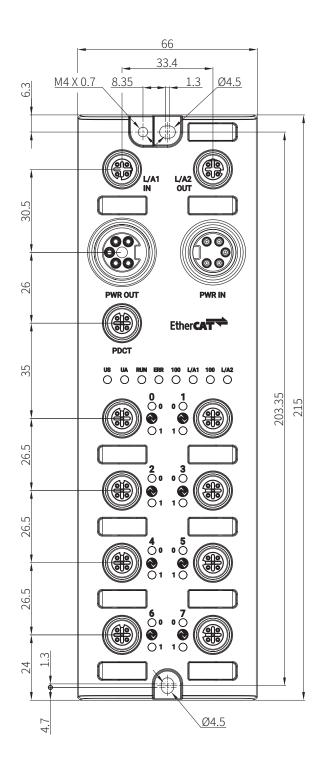
M12 (Socket-Female), A-coded	Pin	Function
	1	Not Connected (N.C.)
1 2	2	Data -
	3	0 V
4 3	4	Not Connected (N.C.)
	5	Data +

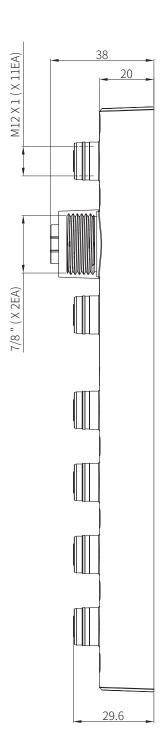
## ■ I/O port

M12 (Socket-Female), A-coded	Pin	Function
	1	+24 VDC===
1 2	2	I/Q: Digital Input
	3	0 V
4 3	4	C/Q: IO-Link, Digital Input/Output
	5	Not Connected (N.C.)

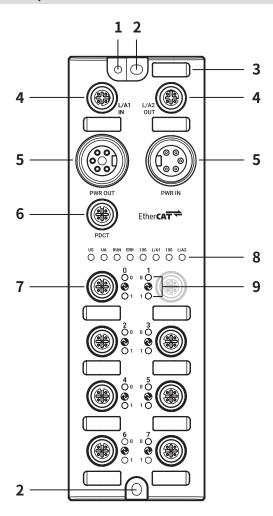
## **Dimensions**

• Unit: mm, For the detailed dimensions of the product, follow the Autonics website.





## **Unit Descriptions**

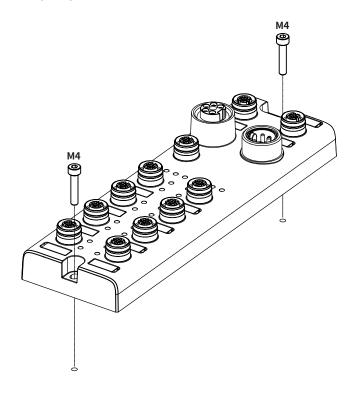


- 01. Grounding hole
- 02. Mounting hole
- 03. Insertion part for the name plate
- 04. Ethernet port
- 05. Power supply port
- 06. PDCT port
- 07. I/O port
- 08. Status indicator
- 09. I/O port indicator

## Installation

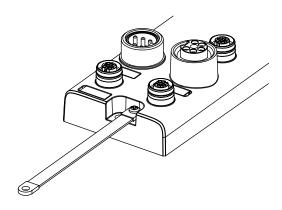
#### **■** Mounting

- 01. Prepare a flat or metal panel in the enclosure.
- 02. Drill a hole to mount and ground the product on the surface.
- 03. Turn off all power.
- 04. Fix the product using M4 screws in the mounting holes. Tightening torque:  $1.5\,\mathrm{N}\,\mathrm{m}$



## **■** Grounding

- $\triangle$  Be sure to use a cable with low impedance and as short as possible for connecting the housing to the product.
- 01. Connect the grounding strap and M4  $\times$  10 screw with washer.
- 02. Fix the screw in the grounding hole. Tightening torque: 1.2 N m



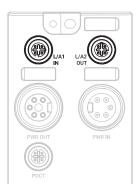
#### **Port Connections**

## ■ Port specifications

 $\bullet \ Be sure to check the port specifications below before connecting the device. Prepare a cable that complies with the protection rating IP67/IP69K. The device of the port of the port of the protection of the port of th$ 

Ethernet port		I/O port	PDCT port	Power supply port
Туре	M12 (Socket-Female), 4-pin, D-coded			Input: 7/8" (Plug-Male), 5-pin Output: 7/8" (Socket-Female), 5-pin
Push-Pull	YES	YES YES YES		N.A
Number of ports	Fports 2 8 1		2	
Tightening torque 0.6 N m 0.6 N m 0.6 N m		0.6 N m	1.5 N m	
Supported function	Daisy chain	-	USB serial communication	Daisy chain

#### 01. Connect to the EtherCAT



01. Connect the M12 connector to the Ethernet port. See the connections below.

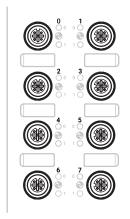


1	TX+	Transmit Data +
2	RX+	Receive Data +
3	TX -	Transmit Data -
4	RX -	Receive Data -

- 02. Connect the connector to the EtherCAT network.
  - Network device: PLC or EtherCAT device supporting EtherCAT protocol
- 03. Put the waterproof cover on the unused port.

## 02. Connect the IO-Link devices

△ The maximum output current is 2 A at each I/O port. Configure the device so that the total current of the I/O ports does not exceed 9 A. △ Check the wiring information in the manual of the IO-Link device to be connected.



01. Connect the M12 connector to the I/O port. See the connections below.

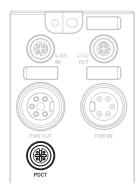


1	+24 VDC==
2	I/Q: Digital Input
3	0 V
4	C/Q: IO-Link, Digital Input/Output
5	Not Connected (N.C.)

02. Put the waterproof cover on the unused port.

#### 03. Connect with the atIOLink

 $\underline{\wedge}$  Do not use the PDCT port and the Ethernet port at the same time.



01. Connect the M12 connector of SCM-USM12, the communication cable for the PDCT port (sold separately), to the PDCT port. See the connections below.



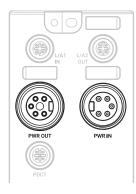
1	Not Connected (N.C.)
2	Data -
3	0 V
4	Not Connected (N.C.)
5	Data +

- 02. Connect the USB connector of the SCM-USM12, the communication cable for the PDCT port (sold separately), to the network device.
  - Network device: PC/laptop that atIOLink software is installed
- 03. Put the waterproof cover on the unused port.

## **Port Connections**

## 04. Connect the power supply to ADIO

 $\underline{\mathbb{A}}$  Be sure not to exceed 9 A of the maximum supplying current to the sensor (US).



- 01. Turn off all power.
- 02. Connect the  $7/8\ensuremath{^{"}}$  connector to the power supply port. See the connections below.





1,2	0 V	Sensor and actuator supply
3	F.G.	Frame ground
4	+24 VDC==	Sensor supply
5	+24 VDC==	Actuator supply

## Indicators

## **■** Status indicator

US	UA	RUN	ERR	100	L/A1	100	L/A2
0	0	0	0	0	0	$\circ$	0

## 01. The power supply of sensor

Indicator	LED Color	Status	Description
	Green	ON	Applied voltage: normal
US	Red	Flashing (1 Hz)	Applied voltage: low (< 18 VDC==)

## ${\bf 02. \ The \ power \ supply \ of \ actuator}$

Indicator	LED Color	Status	Description
UA	Green	ON	Applied voltage: normal
	Red	Flashing (1 Hz)	Applied voltage: low (< 18 VDC==)
		ON	Applied voltage: none (< 10 VDC==)

## 03. Product initialization

Indicator	LED Color	Status	Description
US, UA	Red	ON	ADIO initialization failure

## 04. EtherCAT state machine

Indicator	LED Color	Status	Description
	Green	OFF	EtherCAT state: INIT
		Flashing	EtherCAT state: PRE-OPERATIONAL
RUN		Flashing (once)	EtherCAT state: SAFE-OPERATIONAL
		ON	EtherCAT state: OPERATIONAL

#### 05. Error alert

Indicator	LED Color	Status	Description
	Red	OFF	No error
		Flashing	Invalid configuration
ERR		Flashing (once)	Local error
		ON	Error in application

## 06. Ethernet connection

Indicator	LED Color	Status	Description
L/A1	Green	OFF	No Ethernet connection.
L/A2		ON	The Ethernet connection is established.

## 07. Transmission rate of the Ethernet

Indicator	LED Color	Status	Description
100	Green	ON	Transmission rate: 100 Mbps

## ■ I/O port indicator



## 01. Pin 4 (C/Q)

Indicator	LED Color	Status	Description
	Yellow Green	OFF	DI/DO: pin 4 OFF
		ON	DI/DO: pin 4 ON
		ON	Port configuration: IO-Link
0		Flashing (1 Hz)	Port configuration: IO-Link, No IO-Link device found
	Red	Flashing (2 Hz)	IO-Link configuration error
		ON	Short circuit occurred on pin 4

## 02. Pin 2 (I/Q)

Indicator	LED Color	Status	Description
	Yellow	OFF	DI: pin 2 OFF
1		ON	DI: pin 2 ON

## 03. The power supply of the I/O port

Indicator	LED Color	Status	Description
0,1	Red		Short circuit occurred in the I/O supply power (pin 1, 3)

## **Specifications**

## ■ Electrical/Mechanical specifications

Supply voltage	18 - 30 VDC==
Rated voltage	24 VDC==
Current consumption	2.4 W ( ≤ 216 W)
Supplying current per port	≤ 2 A/Port
Sensor current (US)	≤9A
Dimensions	W 66 × H 215 × D 38 mm
Material	Zinc Die casting
Ethernet port	M12 (Socket-Female), 4-pin, D-coded, Push-Pull Number of ports: 2 (IN/OUT) Supported function: daisy chain
Power supply port	Input: 7/8" (Plug-Male), 5-pin Output: 7/8" (Socket-Female), 5-pin Number of ports: 2 (IN/OUT) Supported function: daisy chain
PDCT port	M12 (Socket-Female), 5-pin, A-coded, Push-Pull Number of ports: 1 Connection method: USB serial communication
I/O port	M12 (Socket-Female), 5-pin, A-coded, Push-Pull Number of ports: 8
Mounting method	Mounting hole: fixed with M4 screw
Grounding method	Grounding hole: fixed with M4 screw
Unit weight (packaged)	≈ 700 g (≈ 900 g)

## **■** Mode specifications

Mode	Digital Input
Number of channels	16-CH (I/Q: 8-CH, C/Q:8-CH)
I/O common	NPN / PNP
Input current	5 mA
ON voltage/current	Voltage: ≥ 15 VDC== Current: ≥ 5 mA
OFF voltage	≤5 VDC==

Mode	Digital Output
Number of channels	8-CH (C/Q)
I/O common	NPN / PNP
Power supply	24 VDC== (18 - 30 VDC==), Max. 300 mA
Leakage current	≤ 0.1 mA
Residual voltage	≤ 1.5 VDC==
Short circuit protection	YES

Mode	IO-Link
Input current	2 mA
ON voltage/current	Voltage: ≥ 15 VDC <del></del> Current: ≥ 2 mA
OFF voltage	≤5 VDC==

## **■** Environmental conditions

Ambient temperature 01)	-5 to 70 °C, Storage: -25 to 70 °C (no freezing or condensation)
Ambient humidity	35 to 75%RH (no freezing or condensation)
Protection rating	IP67 (IEC standard), IP69K (DIN standard)

01) UL approved ambient temperature: 45 °C

## **■** Certification

## **Communication Interface**

#### **■** Ethernet

Ethernet standard	100BASE-TX
Cable spec.	STP (Shielded Twisted Pair) Ethernet cable over Cat 5
Transmission rate	100 Mbps
Cable length	≤ 100 m
Protocol	EtherCAT
ESI file	Downland the ESI file from the Autonics website.

## ■ IO-Link

Version	1.1
Transmission rate	COM1: 4.8 kbps / COM2: 38.4 kbps / COM3: 230.4 kbps
Port class	Class A
Standard	IO-Link Interface and System Specification Version 1.1.2 IO-Link Test Specification Version 1.1.2

## Sold Separately: SCM-USM12 (Comm. Cable for PDCT Port)

## ■ Specifications

Connector 1	Connector 2	Length	Feature
1 2 3 4	$\begin{pmatrix} 2 \bullet & 5 \bullet 1 \\ \bullet & \bullet \\ 3 & \bullet & 4 \end{pmatrix}$	2 m	• IP20 / IP67 • PVC
USB Type A (Plug-Male), 4-pin	M12 (Plug-Male), 5-pin, A-coded		

#### Connection

Connec	Connector 1	
Pin no.	Function	
1	0 V	
2	Data+	
3	Data -	
4	+5 VDC==	
-	-	

	Connector 2	
	Pin no.	Function
>	3	0 V
<b>+</b>	5	Data +
>	2	Data -
	1	Not Connected (N.C.)
	4	Not Connected (N.C.)

#### Dimensions

 $\bullet$  Unit: mm, For the detailed dimensions of the product, follow the Autonics website.

